

Data Structures and Languages for General Intelligence



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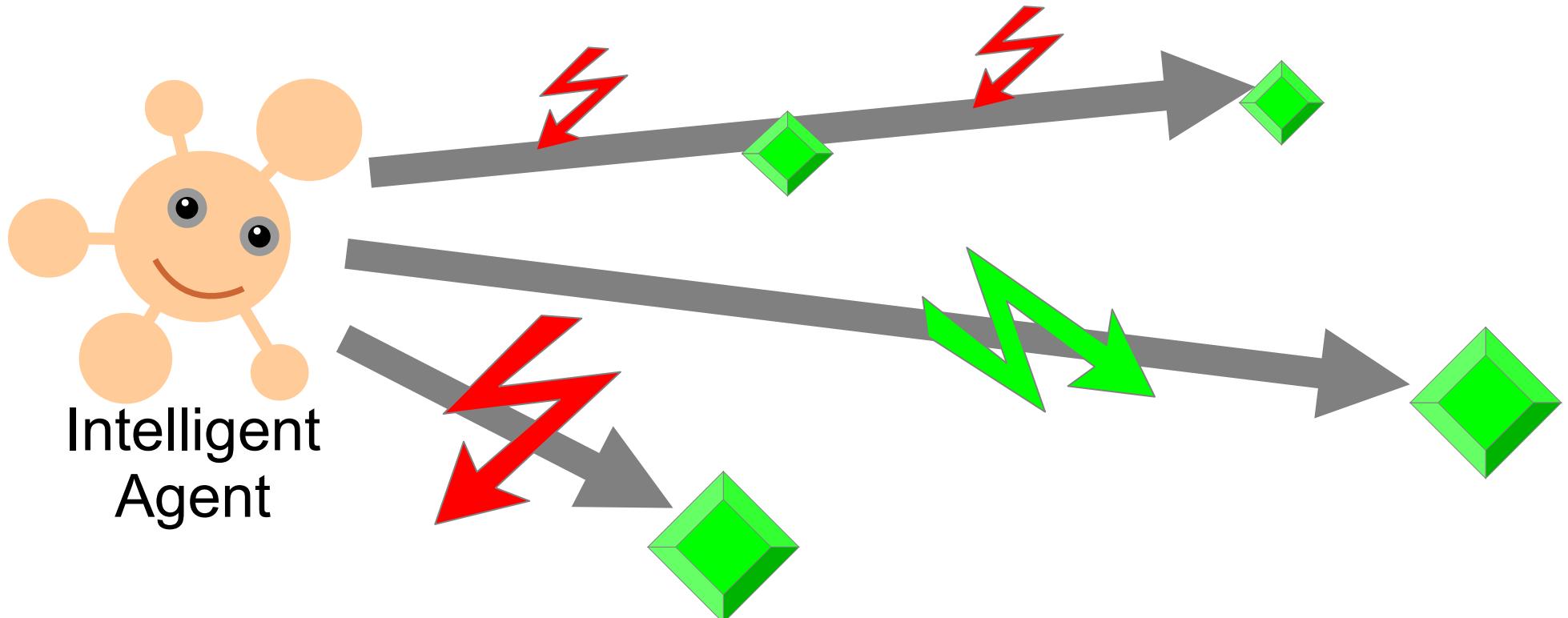
<https://facebook.com/groups/agirussia>
<https://t.me/agirussia>



General Intelligence:

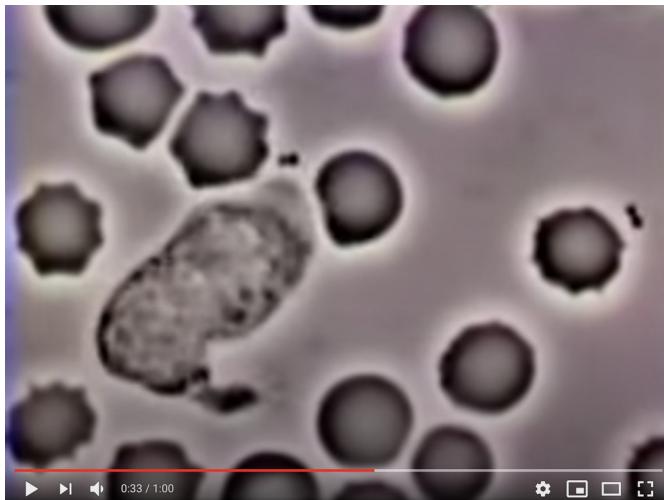
Reaching complex goals in
different complex environments, using
limited resources and minimizing risks

(Ben Goertzel + Pei Wang + Shane Legg + Marcus Hutter)



What is the minimally viable natural system capable to satisfy the requirement?

Single cell organism



Simple nervous system

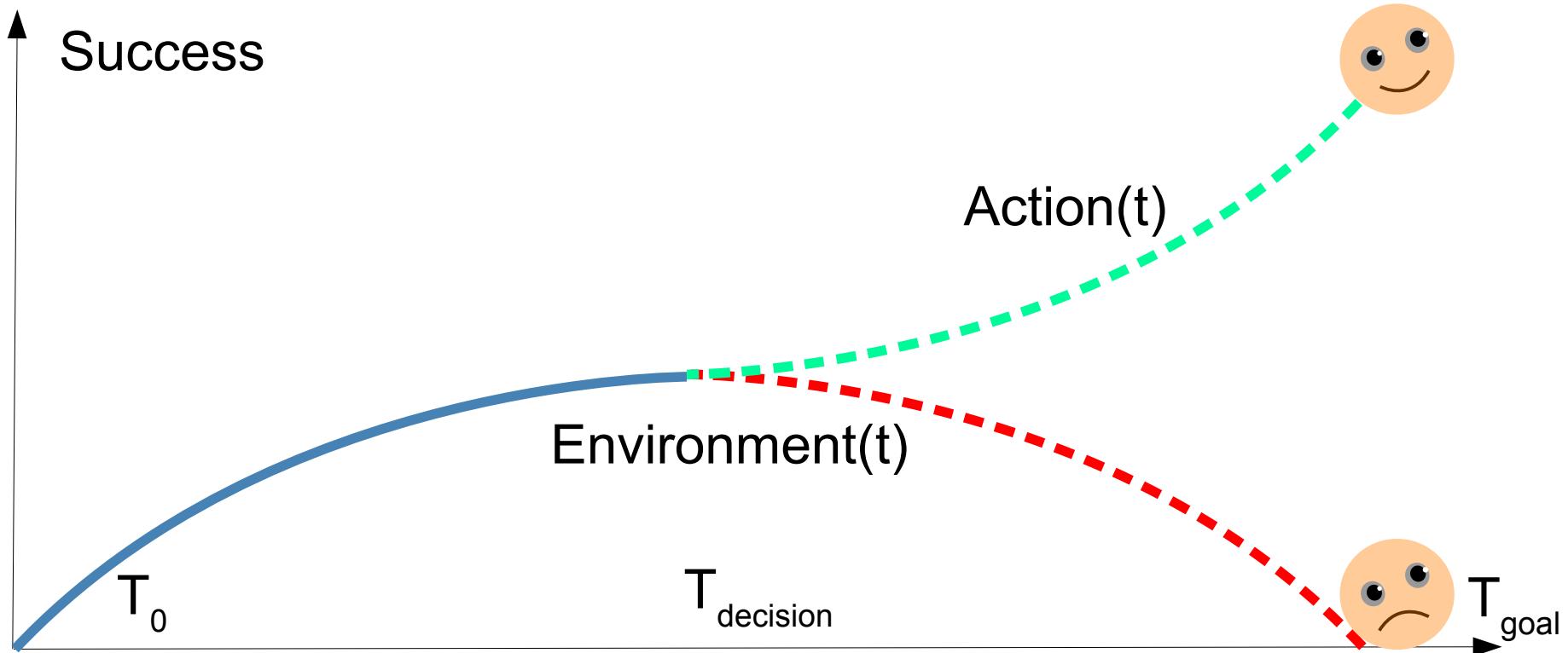


Complex nervous system



Consciousness:

Ability to build models of the environment based on the past to predict the future scenarios and act “consciously” towards the desired ones



Acting consciously:

Agent being able to direct the sequence of behavioral acts (at least) to itself by any (internal or external) language (ontology/lexicon/grammar)



Push legs,
pull right hand

```
push(right_leg);  
push(left_leg);  
pull(right_hand).
```



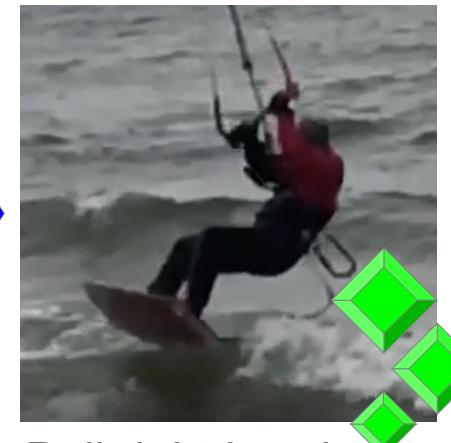
Push left leg,
pull both hands

```
push(left_leg);  
pull(right_hand);  
pull(left_hand).
```



Pull left hand,
look right.

```
look(right);  
pull(left_hand).
```

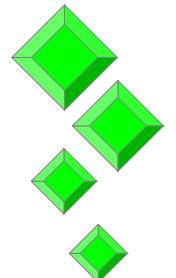


Pull right hand,
bend both legs.

```
pull(right_hand);  
bend(right_leg);  
bend(left_leg).
```

<https://www.youtube.com/watch?v=oYWjqTP0AKM>

Learning with experiential feedback



push(right_leg);
push(left_leg);
push(right_hand).

push(right_leg);
push(left_leg);
pull(right_hand).

push(right_leg);
push(left_leg);
pull(right_hand).

push(right_leg);
push(left_leg);
pull(right_hand).

feel(upset).

push(left_leg);
pull(right_hand).

push(left_leg);
pull(right_hand);
pull(left_hand).

push(left_leg);
pull(right_hand);
pull(left_hand).

feel(upset).

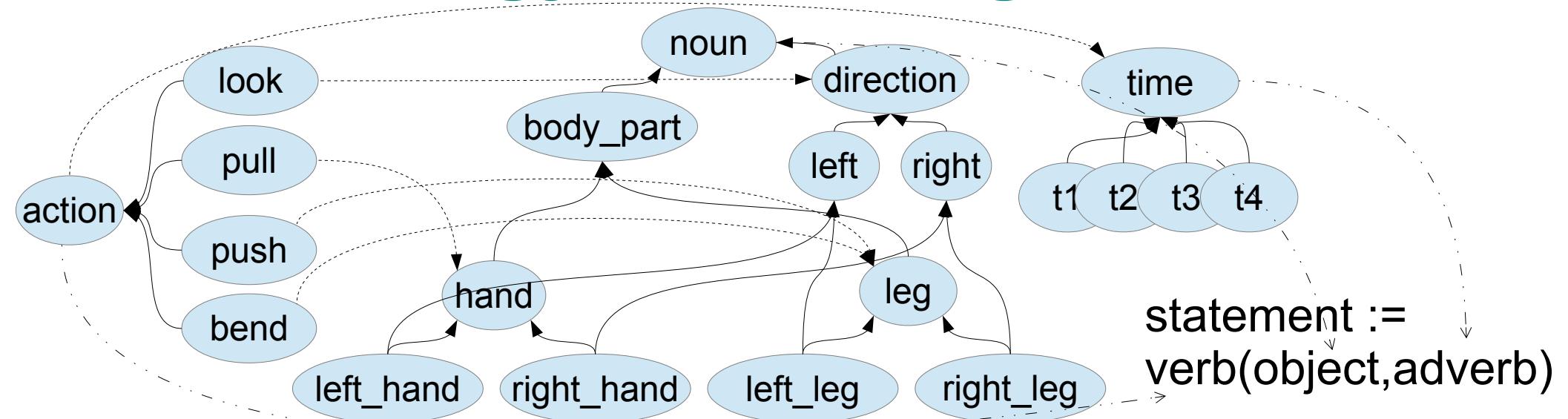
pull(right_hand).
feel(upset).

look(right);
pull(left_hand).
pull(right_hand);
bend(right_leg);
bend(left_leg).

feel(lucky).

<https://www.youtube.com/watch?v=oYWjqTP0AKM>

Ontology, lexicon, grammar



`push(right_leg, t1);
push(left_leg, t1);
pull(right_hand, t1).`



`push(left_leg, t2);
pull(right_hand, t2);
pull(left_hand, t2);
greater(t2,t1);`



`look(right,t3);
pull(left_hand,t3);
greater(t3,t2);`



`pull(right_hand,t4);
bend(right_leg,t4);
bend(left_leg,t4);
greater(t4,t3).`

<https://www.youtube.com/watch?v=oYWjqTP0AKM>

N-ary and higher-order predicates



```
push(right_leg, t1);  
push(left_leg, t1);  
pull(right_hand, t1).
```

```
push(right, leg, t1);  
push(left, leg, t1);  
pull(right ,hand, t1).
```

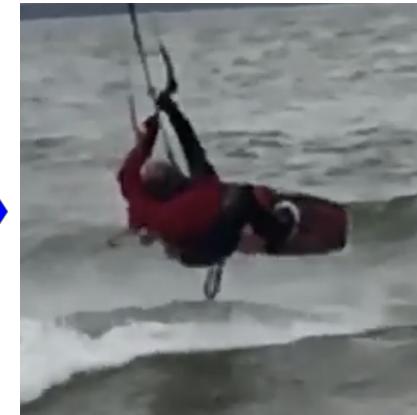
```
before(  
and(  
push(right, leg),  
push(left, leg),  
pull(right ,hand)),  
and(  
push(left, leg),  
pull(right, hand),  
pull(left, hand))).
```



```
push(left_leg, t2);  
pull(right_hand, t2);  
pull(left_hand, t2);  
greater(t2,t1);
```

```
push(left, leg, t2);  
pull(right, hand, t2);  
pull(left, hand, t2);  
greater(t2,t1);
```

```
before(  
and(  
push(left, leg),  
pull(right, hand),  
pull(left, hand)),  
and(  
look(right),  
pull(left, hand))).
```



```
look(right,t3);  
pull(left_hand,t3);  
greater(t3,t2);
```

```
look(right,t3);  
pull(left, hand,t3);  
greater(t3,t2);
```

```
before(  
and(  
look(right),  
pull(left, hand)),  
and(  
pull(right, hand,t4),  
bend(right, leg,t4),  
bend(left, leg,t4))).
```



```
pull(right_hand,t4);  
bend(right_leg,t4);  
bend(left_leg,t4);  
greater(t4,t3).
```

```
pull(right, hand,t4);  
bend(right, leg,t4);  
bend(left, leg,t4);  
greater(t4,t3).
```

Making predicates untyped binary



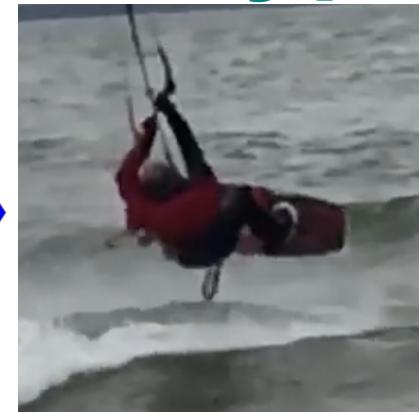
```
push(right_leg, t1);  
push(left_leg, t1);  
pull(right_hand, t1).
```

```
($A,push);  
($A,right_leg);  
($A,t1);  
($B,push);  
($B,left_leg);  
($B,t1);  
($C,pull);  
($C,right_hand);  
($C,t2).
```



```
push(left_leg, t2);  
pull(right_hand, t2);  
pull(left_hand, t2);  
greater(t2,t1).
```

```
($D,push);  
($D,left_leg);  
($D,t2);  
($E,pull);  
($E,right_hand);  
($E, t2);  
($F,pull);  
($F, left_hand);  
($F,t2);  
(t2,t1).
```



```
look(right,t3);  
pull(left_hand,t3);  
greater(t3,t2).
```

```
($G,look);  
($G,right)  
($G,t3);  
($H,pull);  
($H, left_hand)  
($H,t3);  
(t3,t2).
```



```
pull(right_hand,t4);  
bend(right_leg,t4);  
bend(left_leg,t4);  
greater(t4,t3).
```

```
($I,pull);  
($I,right_hand);  
($I,t4);  
($J,bend);  
($J,right_leg)  
($J,t4);  
($K,bend);  
($K, left_leg);  
($K,t4);  
(t4,t3).
```

Attaching probabilities



```
push(right_leg, t1);  
push(left_leg, t1);  
pull(right_hand, t1).
```

```
push(right_leg, t1)  
<0.7>;  
push(left_leg, t1)  
<0.7>;  
pull(right_hand, t1)  
<1.0>.
```

```
push(right_leg,t1,0.7);  
push(left_leg,t1,0.7);  
pull(right_hand,t1,1.0).
```

```
push(left_leg, t2);  
pull(right_hand, t2);  
pull(left_hand, t2);  
greater(t2,t1).
```

```
push(left_leg, t2)  
<1.0>;  
pull(right_hand, t2)  
<1.0>;  
pull(left_hand, t2)  
<0.8>;  
greater(t2,t1,1.0)<1.0>;
```

```
push(left_leg, t2,1.0);  
pull(right_hand, t2,1.0);  
pull(left_hand, t2,0.8);  
greater(t2,t1,1.0);
```

```
look(right,t3);  
pull(left_hand,t3);  
greater(t3,t2).
```

```
look(right,t3)  
<0.9>;  
pull(left_hand,t3)  
<1.0>;  
greater(t3,t2)<1.0>;
```

```
look(right,t3,0.9);  
pull(left_hand,t3,1.0);  
greater(t3,t2,1.0);
```

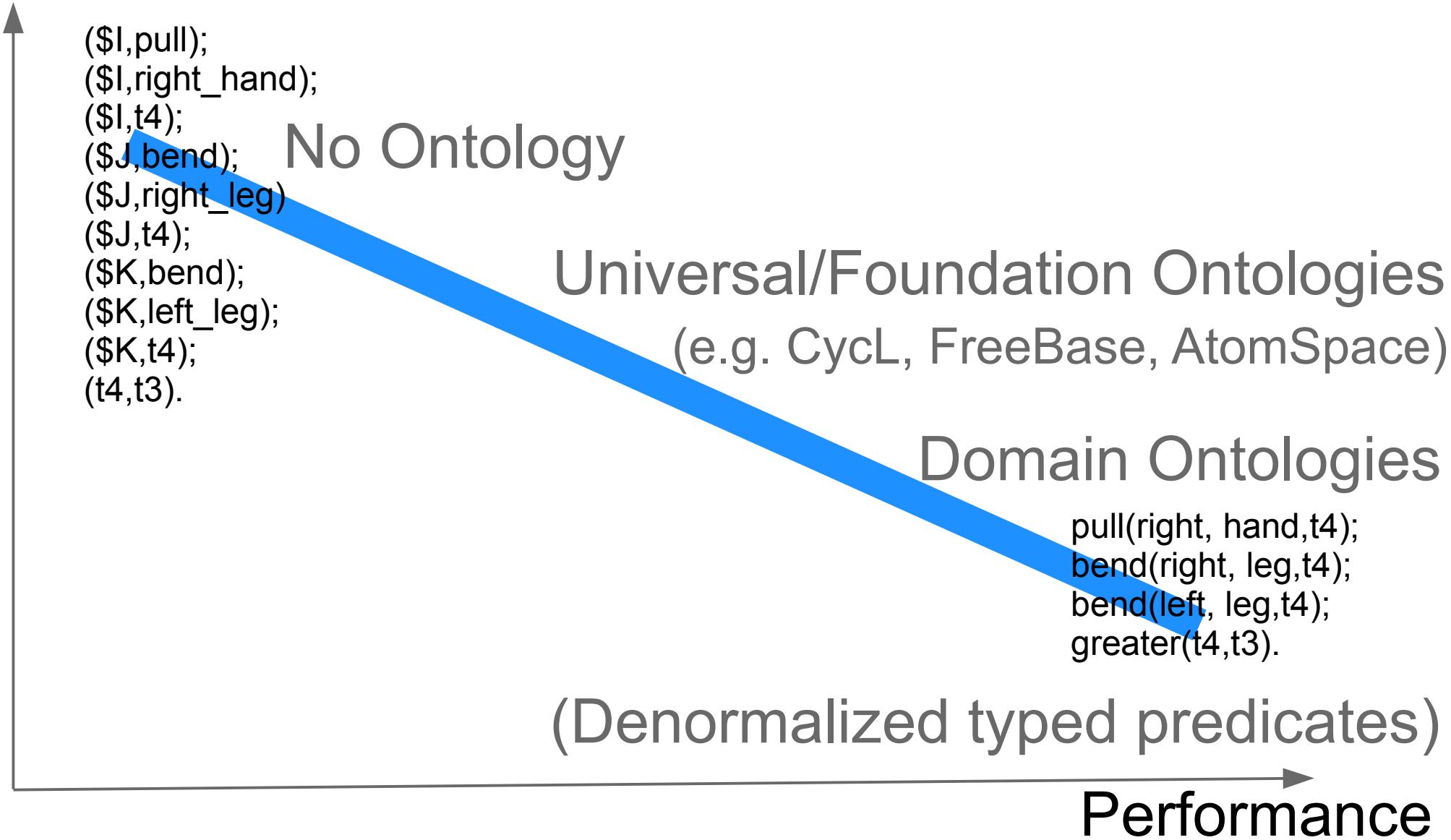
```
pull(right_hand,t4);  
bend(right_leg,t4);  
bend(left_leg,t4);  
greater(t4,t3).
```

```
pull(right_hand,t4);  
<1.0>  
bend(right_leg,t4)  
<0.6>;  
bend(left_leg,t4)  
<0.6>;  
greater(t4,t3)<1.0>.
```

```
pull(right_hand,t4,1.0);  
bend(right_leg,t4,0.6);  
bend(left_leg,t4,0.6);  
greater(t4,t3,1.0).
```

Predicate/Link Arity and Normalization Tradeoff

Flexibility (Normalized untyped predicates)

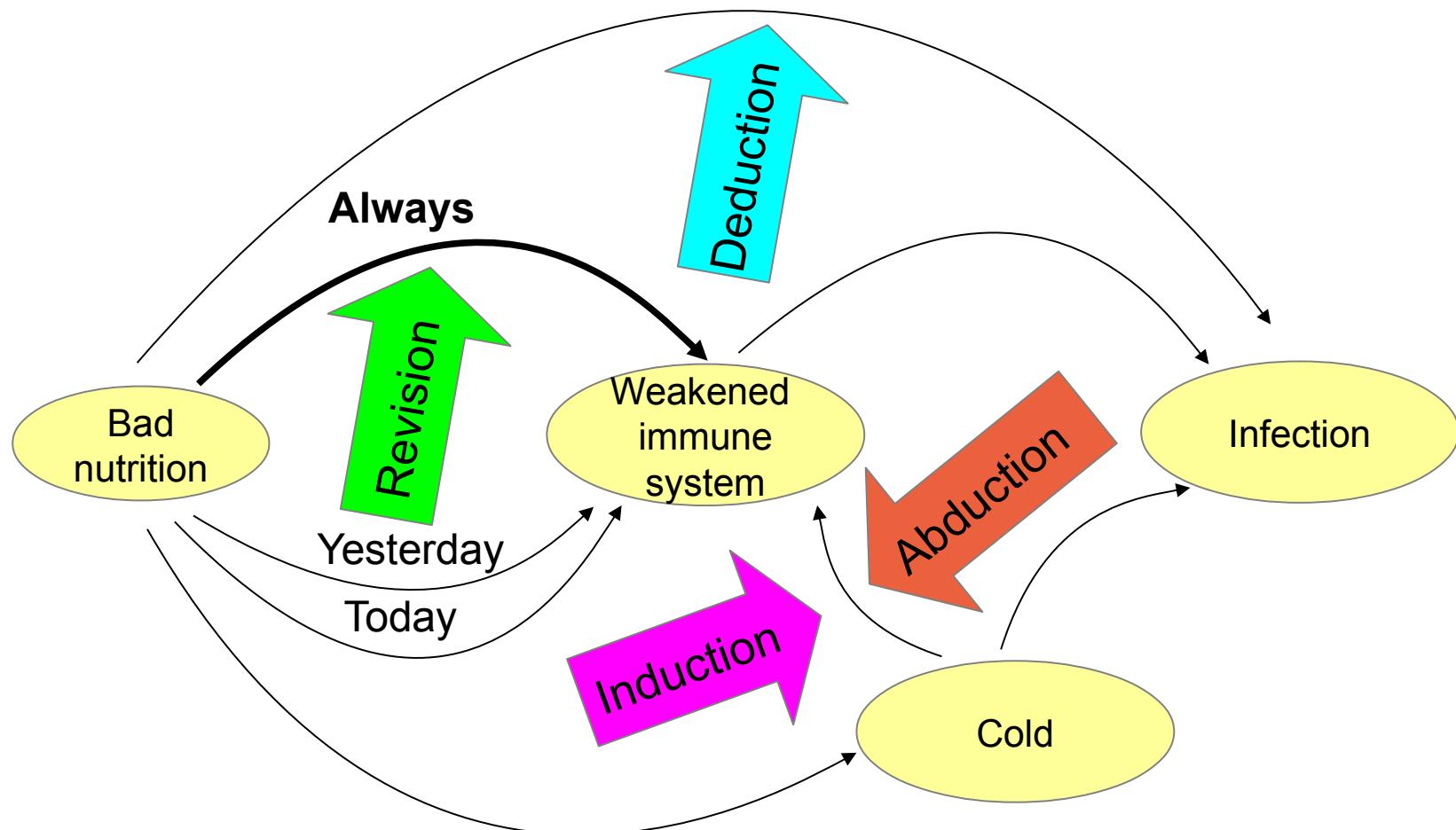


Making Probabilistic Inferences based on Predicates

P.Wang, et. al. (1993-2020) Non-Axiomatic Reasoning System (NARS)

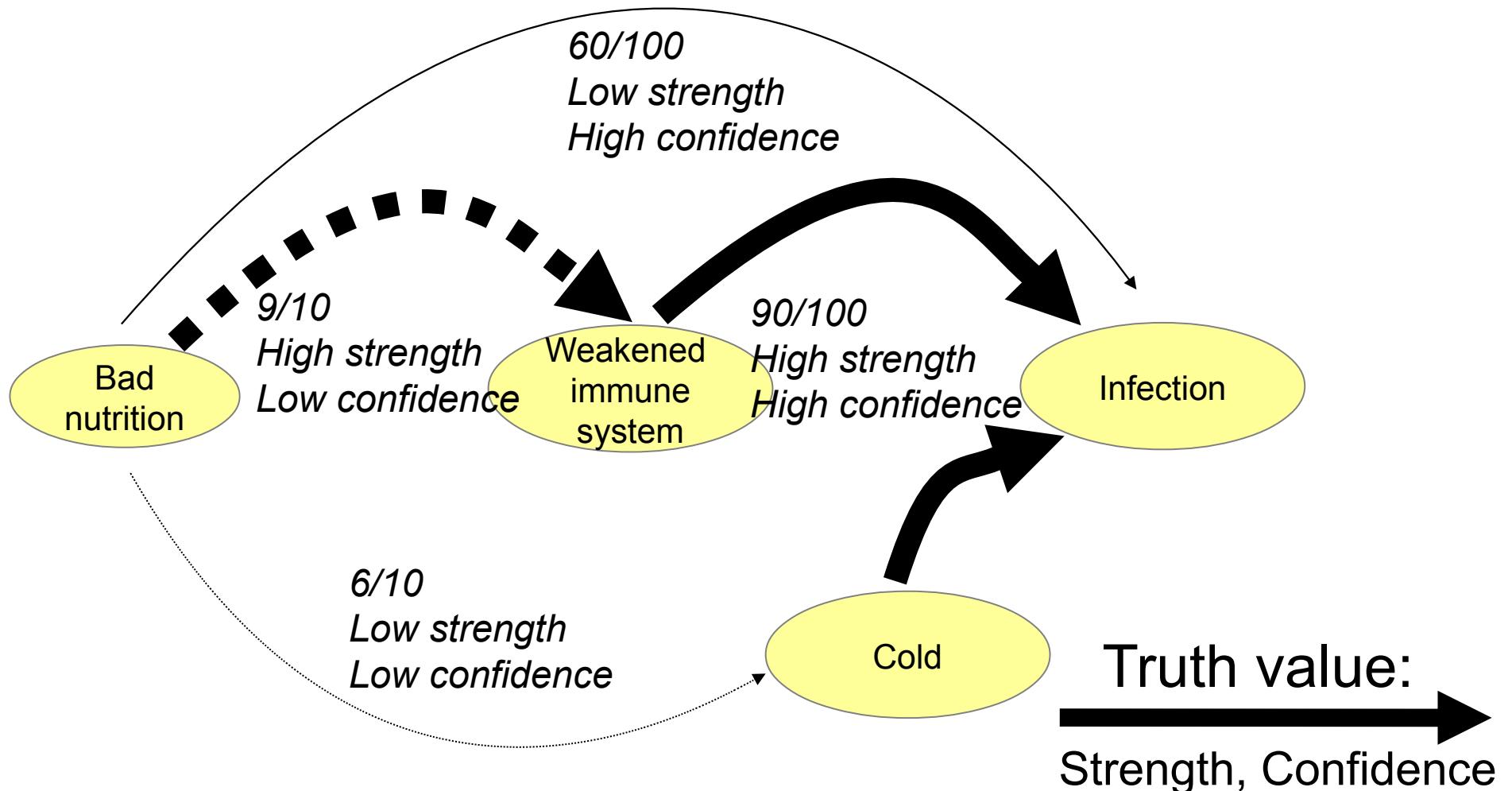
E.Vityaev et.al. (2006-2020) Logical Prediction System (“Discovery”)

B. Goertzel et. al. (2008-2020) Probabilistic Logic Network (PLN)



Replacing Probabilities with Compound Truth Values

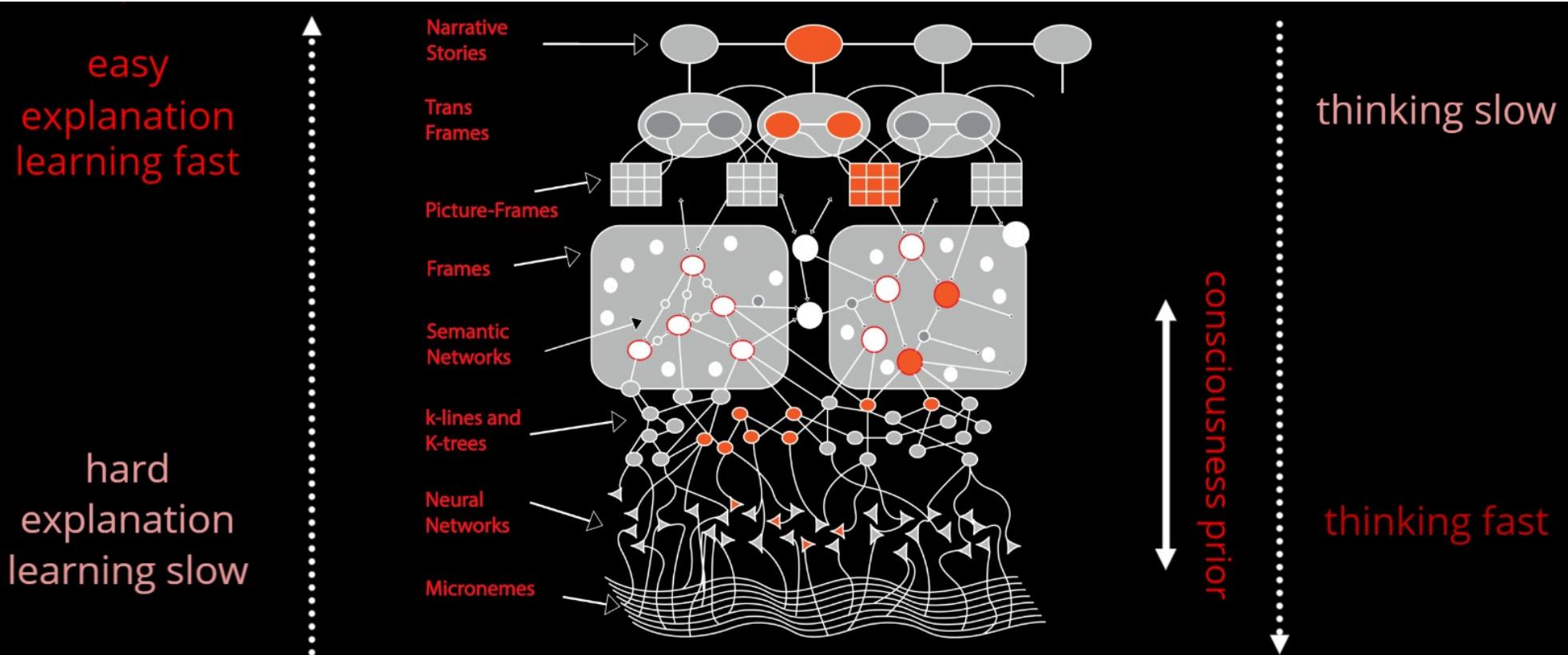
P.Wang, et. al. (1993-2020) Non-Axiomatic Reasoning System (NARS)
B. Goertzel et. al. (2008-2020) Probabilistic Logic Network (PLN)



Hybrid Neuro-Symbolic Cognitive Architectures

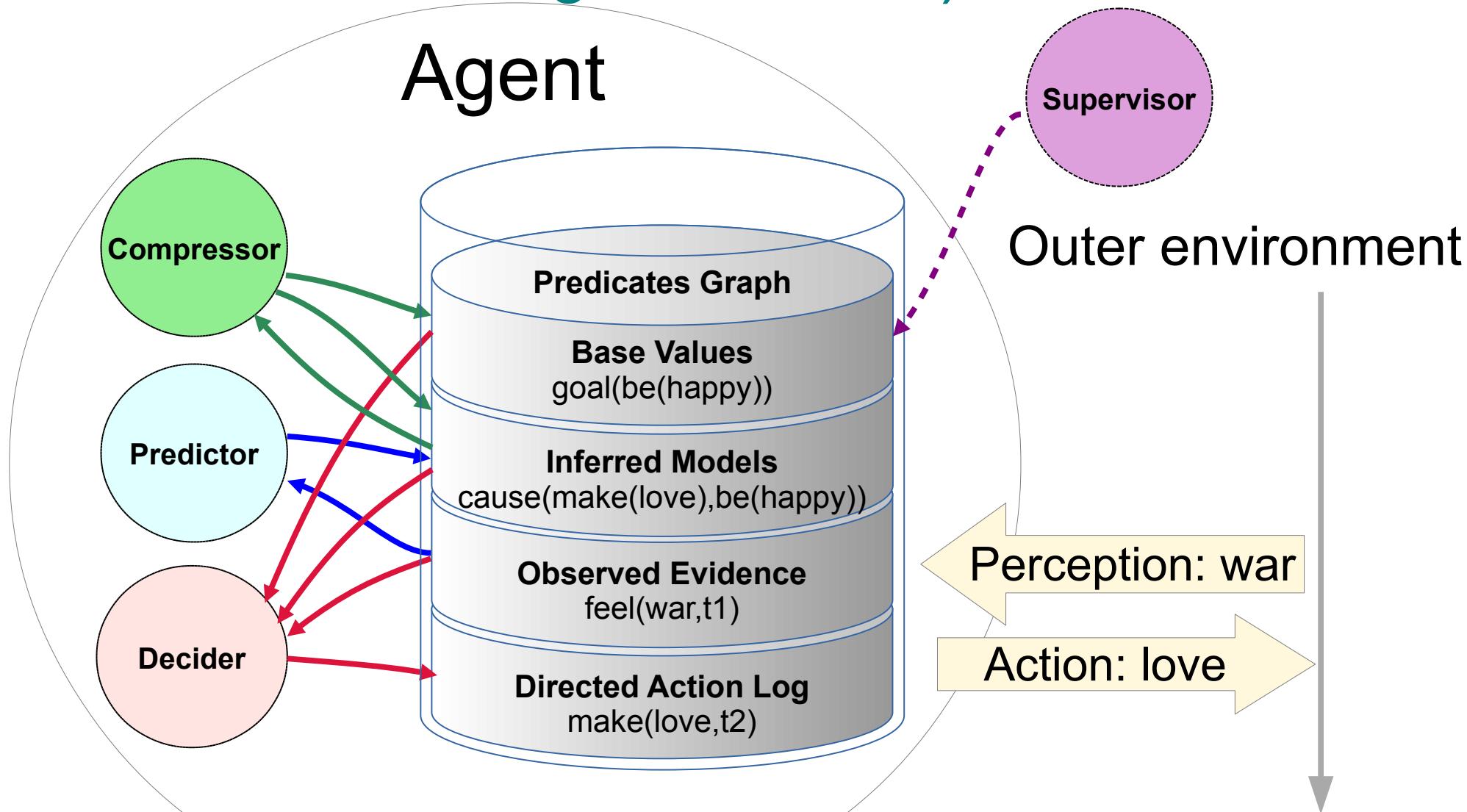
Society of Mind – Marvin Minsky

Thinking, Fast and Slow – Daniel Kahneman



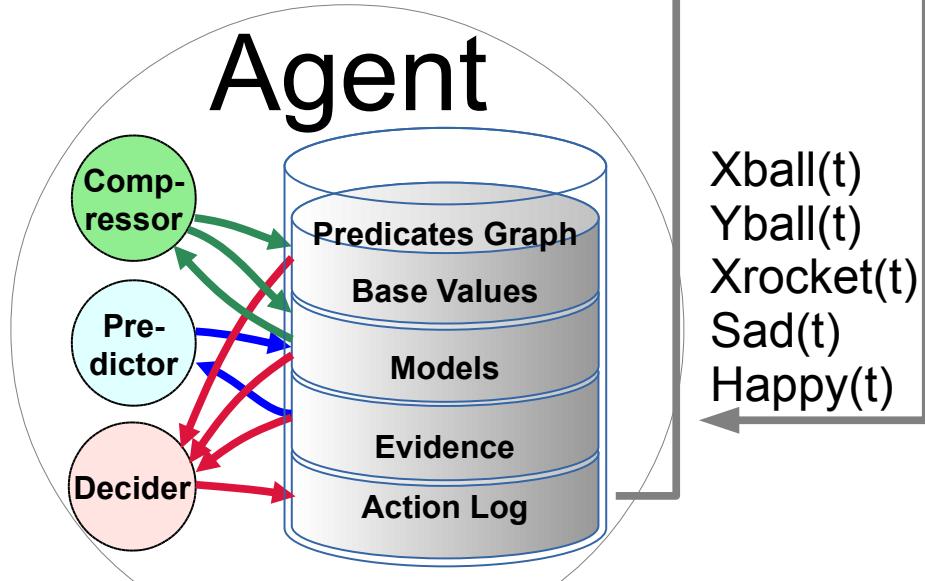
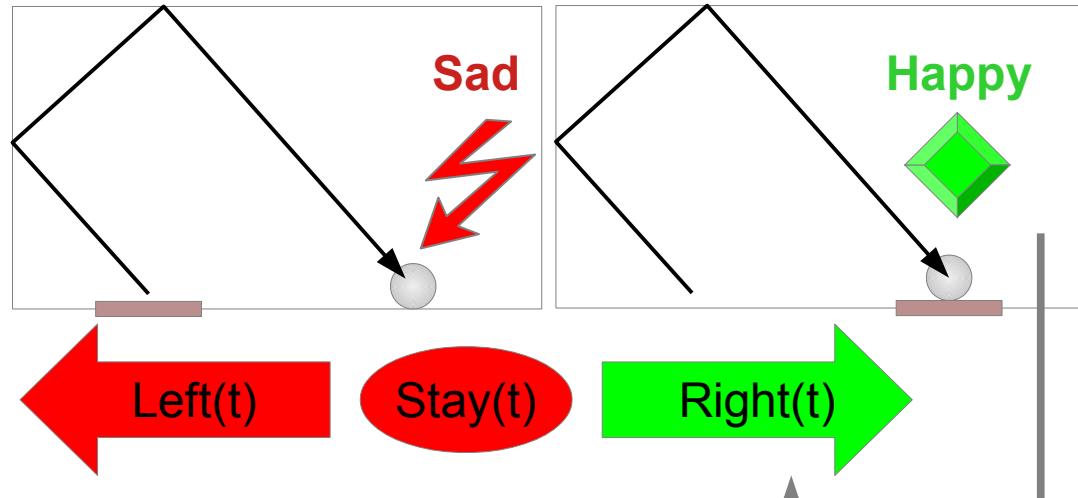
<https://towardsdatascience.com/explainable-ai-vs-explaining-ai-part-1-d39ea5053347>

AGI Agent Cognitive Architecture (and AGI-unit testing framework) based on TFS



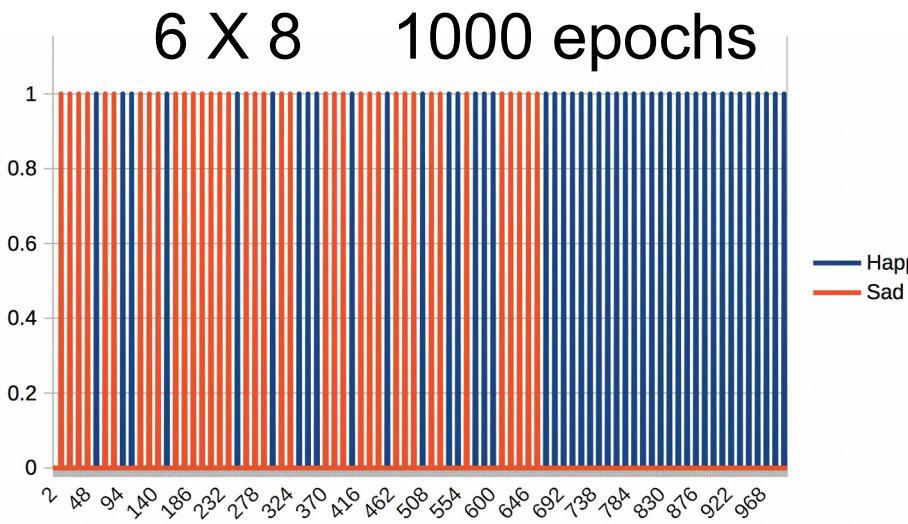
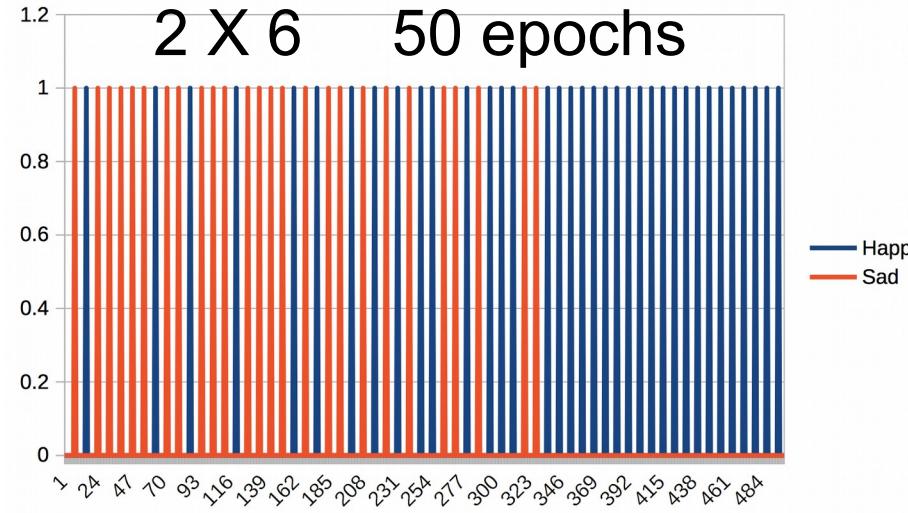
Evgenii E. Vityaev Purposefulness as a Principle of Brain Activity // Anticipation: Learning from the Past, (ed.) M. Nadin. Cognitive Systems Monographs, V.25, Chapter No.: 13. Springer, 2015, pp. 231-254.

AGI Agent Cognitive Architecture learning simplified “Atari Breakdown” game

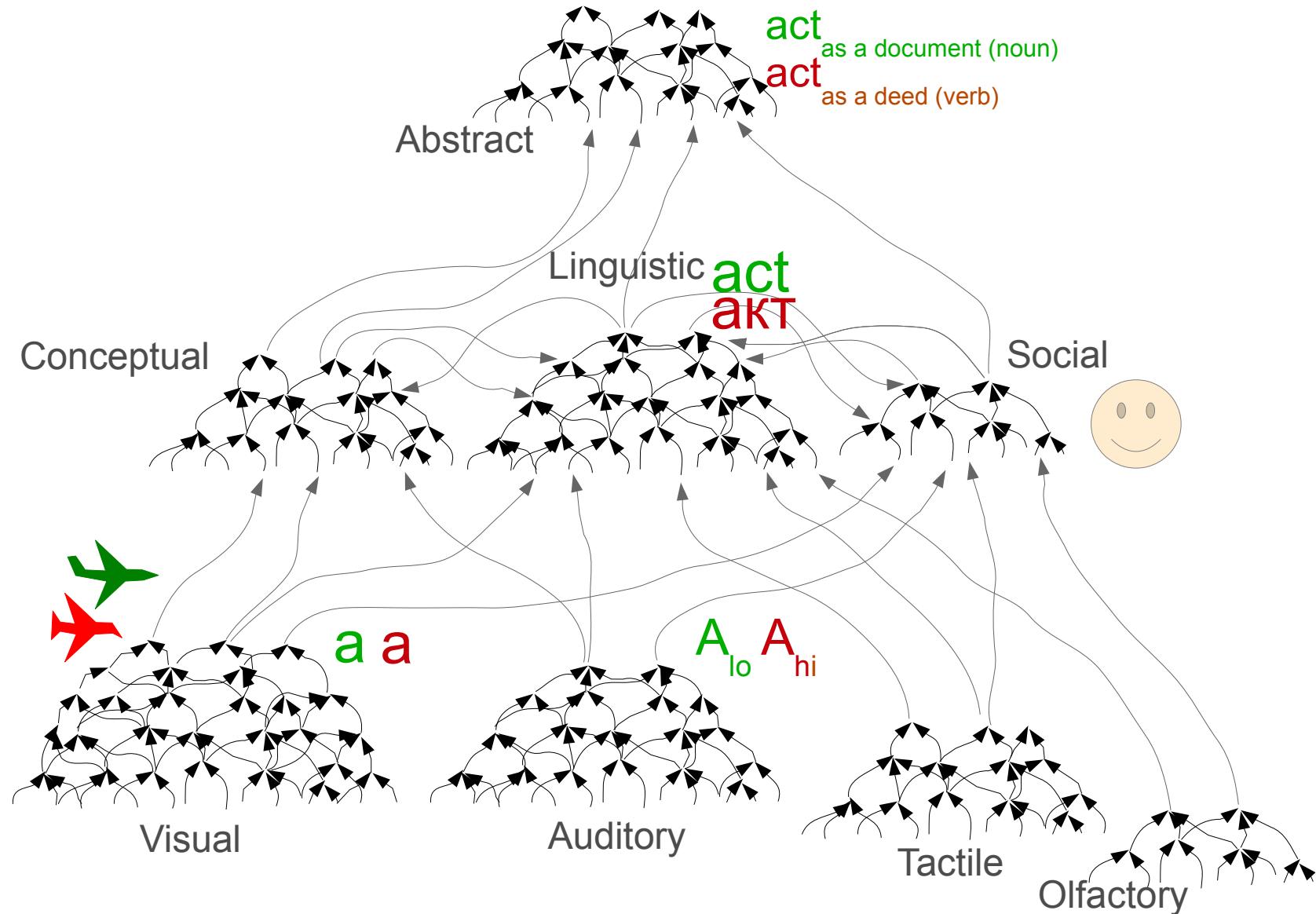


<https://arxiv.org/abs/1807.02072>

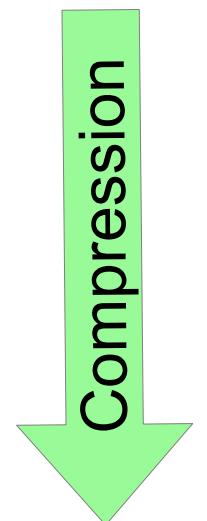
<https://github.com/aigents/aigents-java/blob/master/src/main/java/net/webstructor/util/AgiTester.java>



Physiological Plausibility – different segments of cortex responsible for different level of abstractions



Multi-layer transformation of complexity



$16 \times 16 = 256$ pixels

23K characters

370K words

∞ sentences

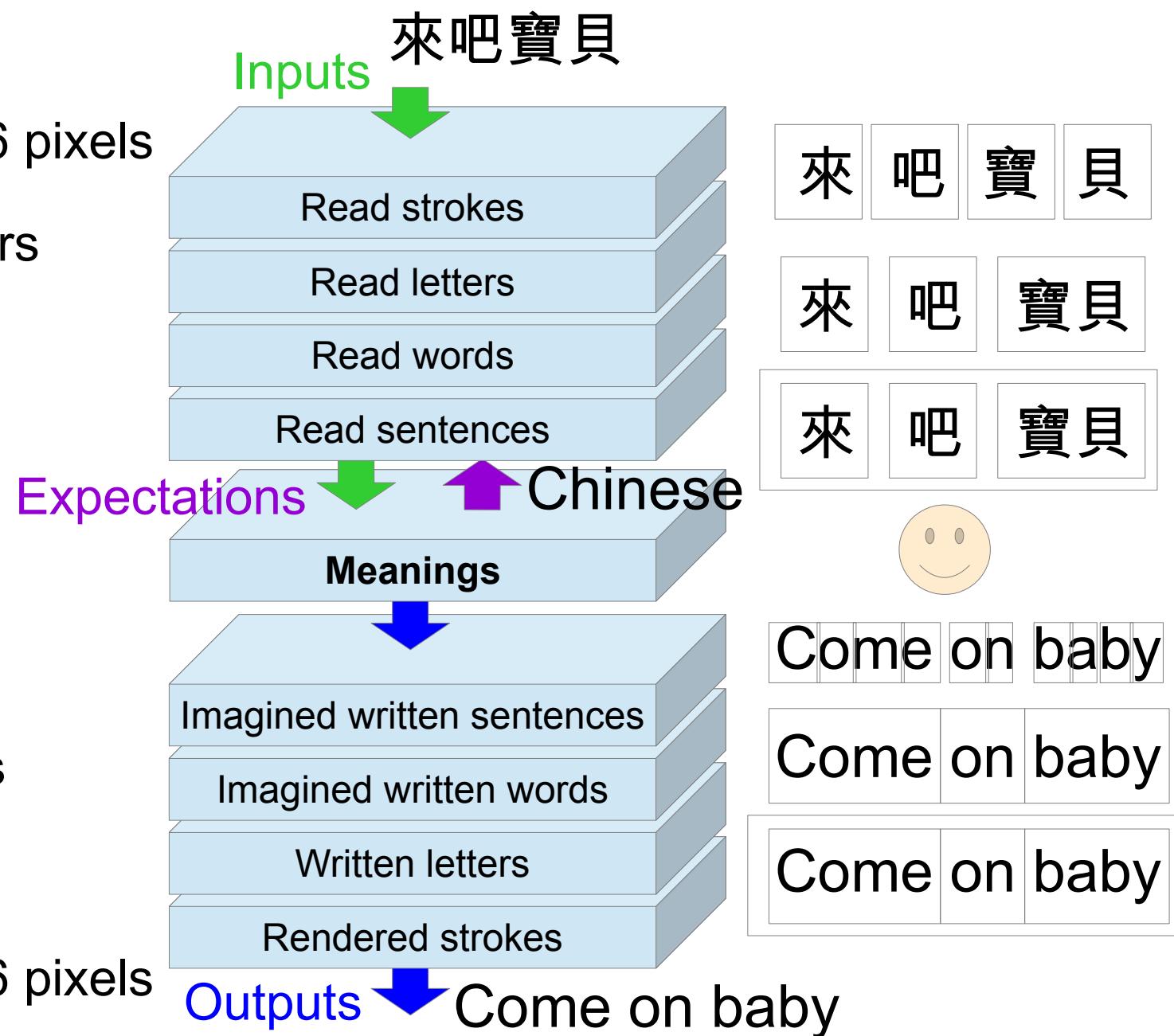


∞ sentences

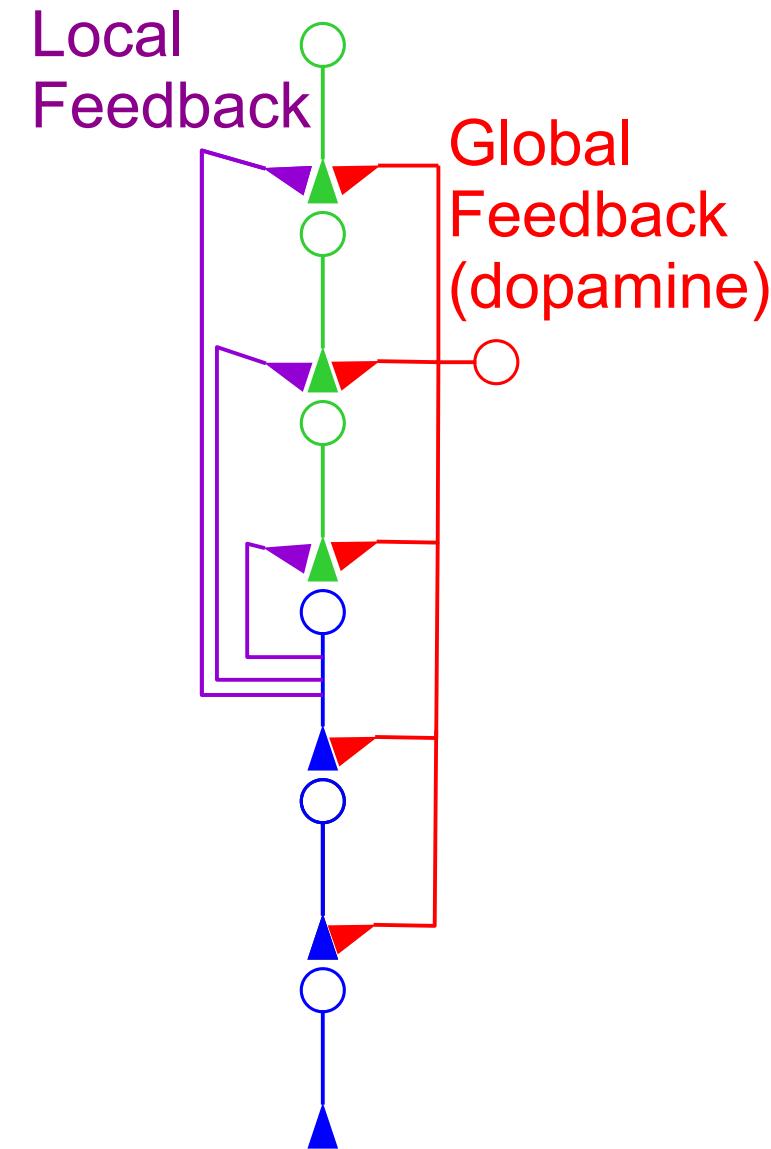
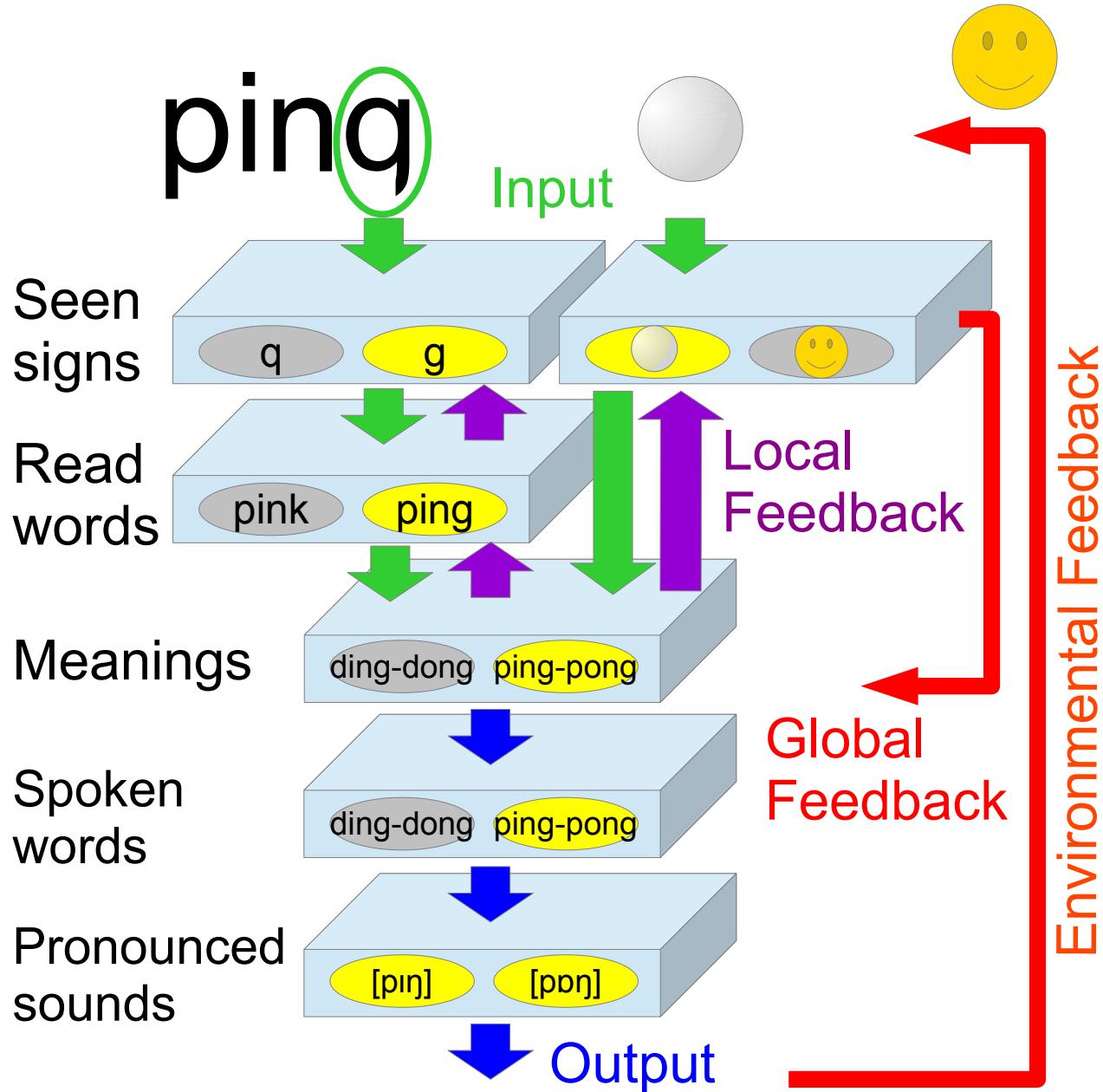
26 characters

170K words

$16 \times 16 = 256$ pixels

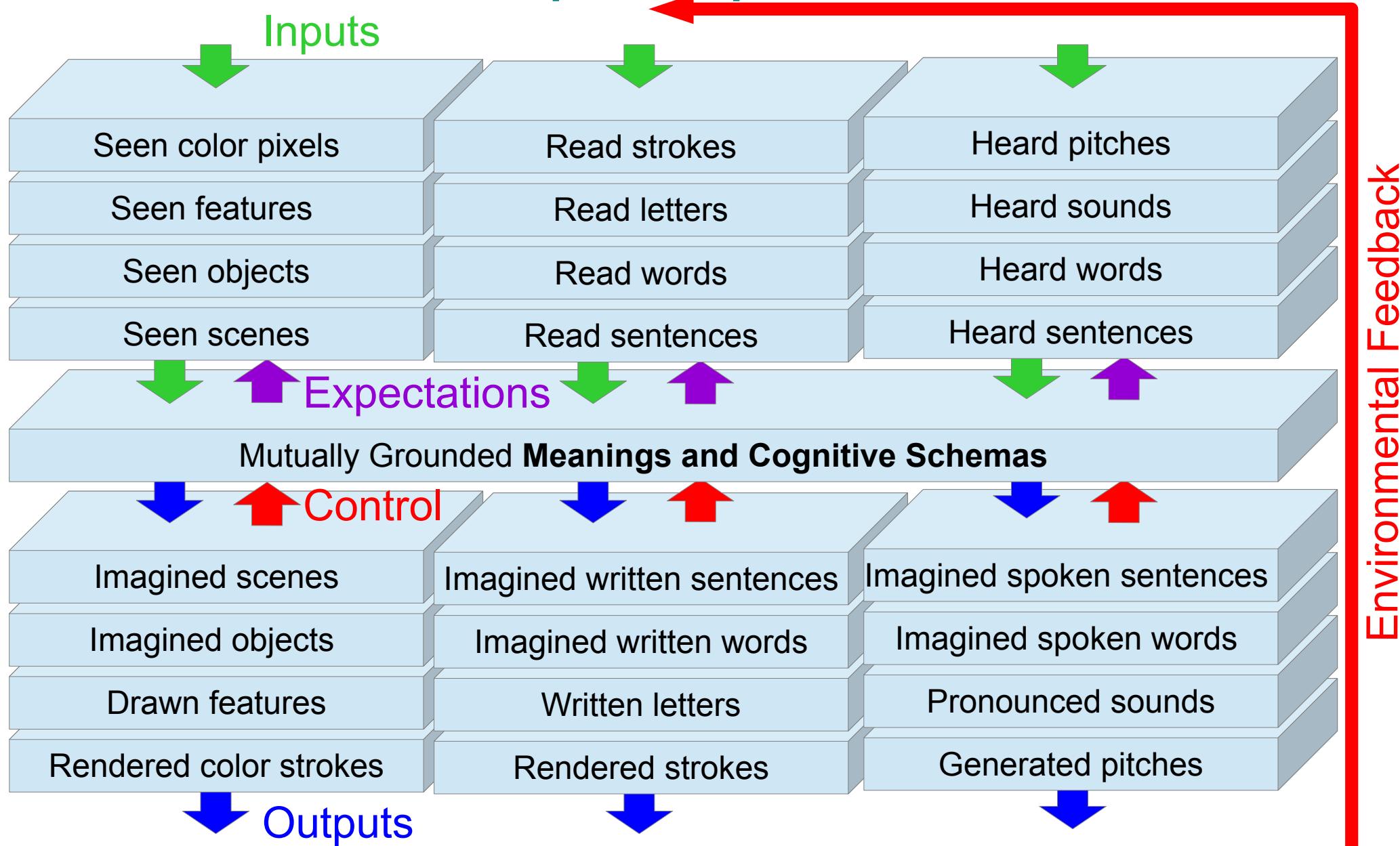


Local and Global Feedback



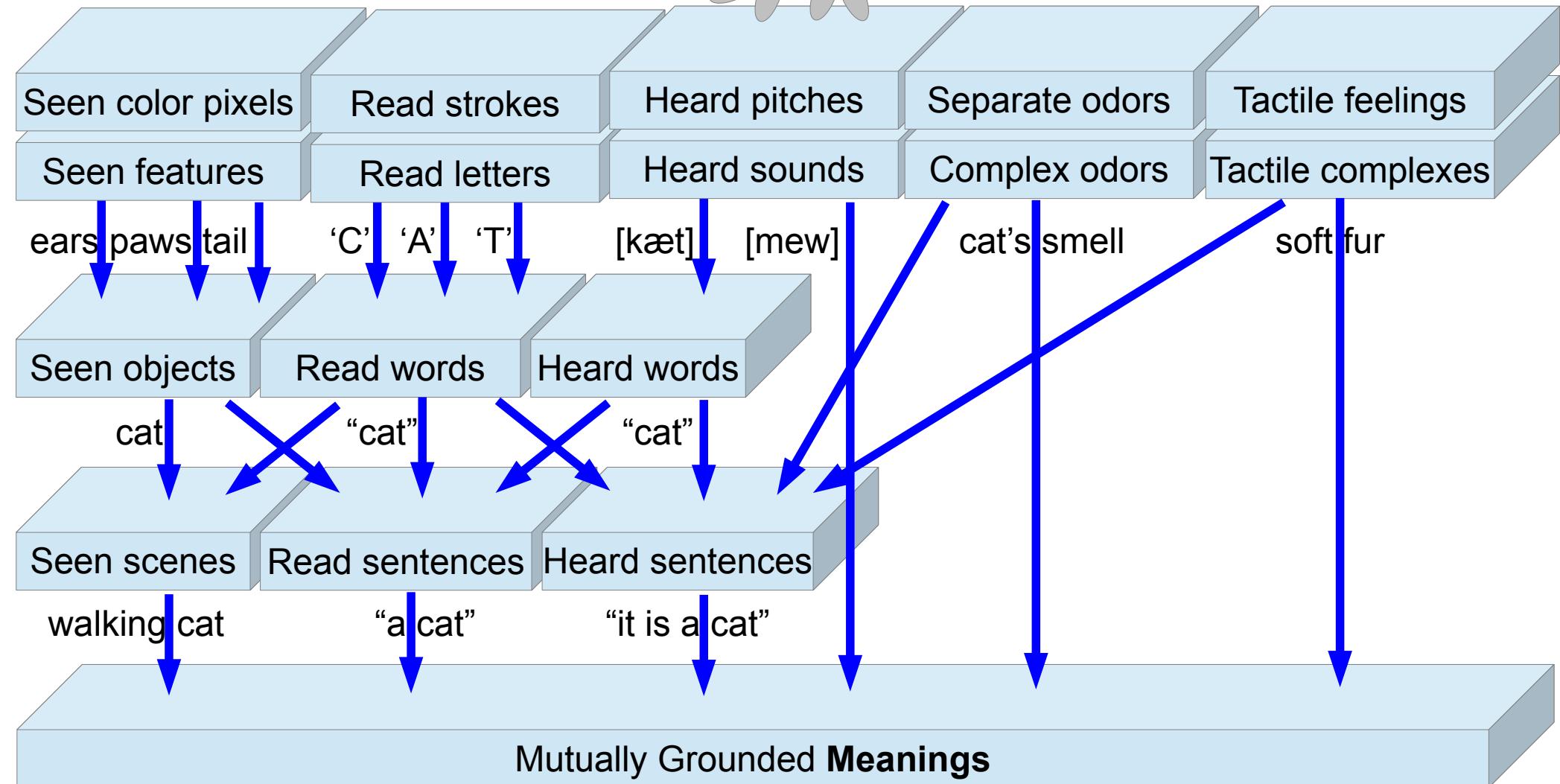
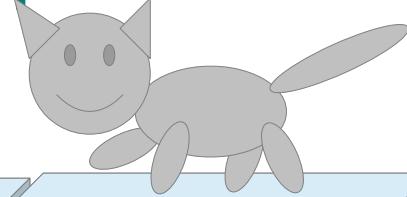
<http://www.acad.bg/ebook/ml/Society%20of%20Mind.pdf> ("Global and Local Reward")

Multi-modal perception and action



<https://www.abiresearch.com/blogs/2019/10/10/multimodal-learning-artificial-intelligence/>

Multi-modal perception + mutual grounding



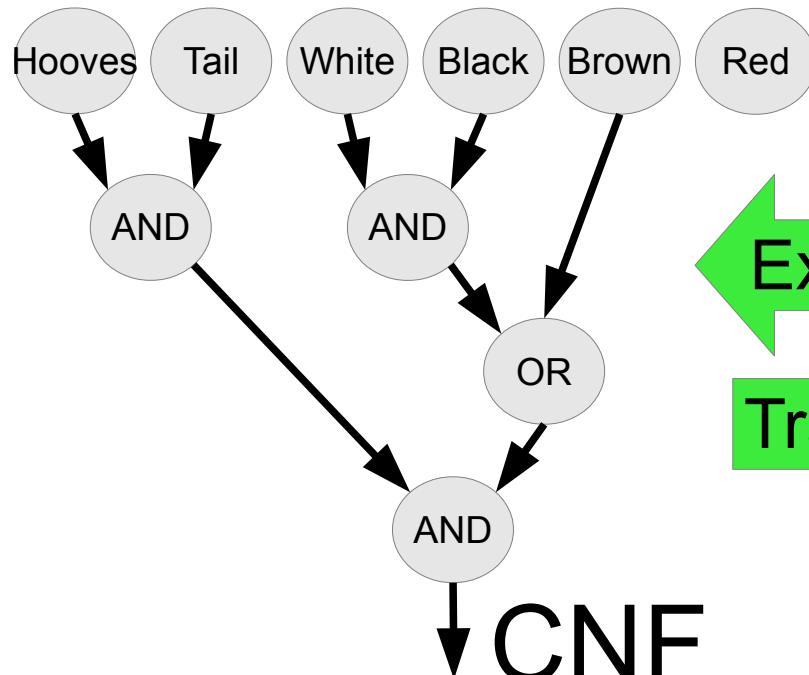
This walking cat is mewing!

<https://www.abiresearch.com/blogs/2019/10/10/multimodal-learning-artificial-intelligence/>

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Bridging the Symbolic-Subsymbolic gap for “explainable AI” and “transfer learning”

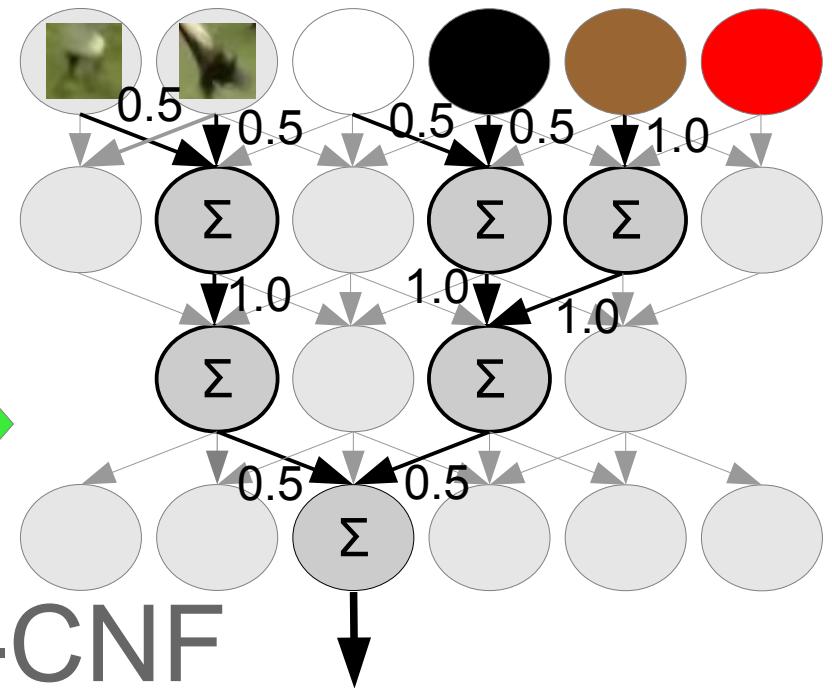
Labeled graph



(Hooves AND Tail) AND
(White and Black) OR Brown)

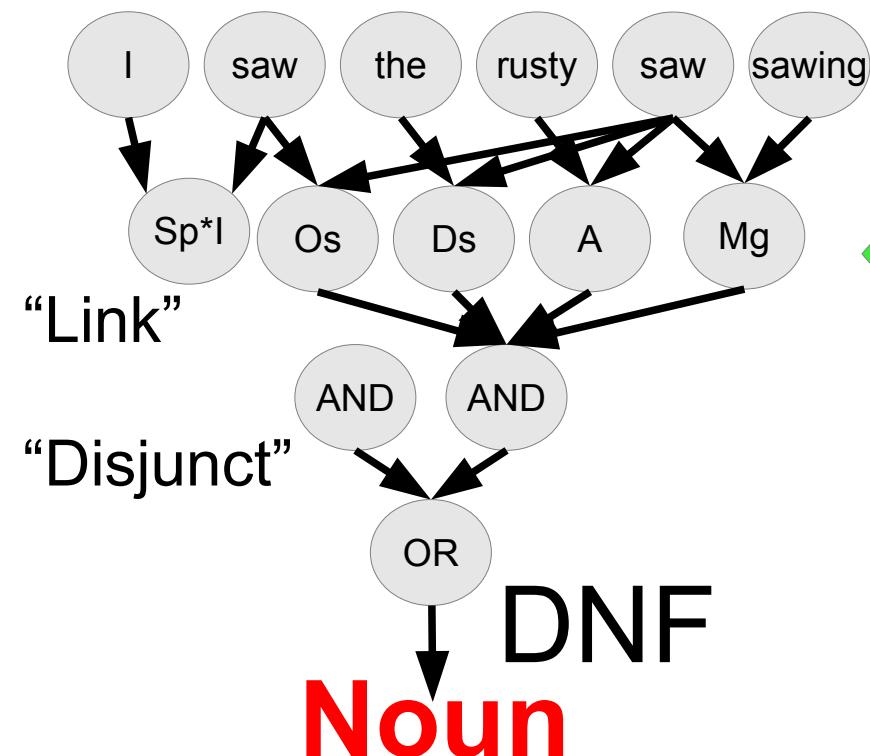
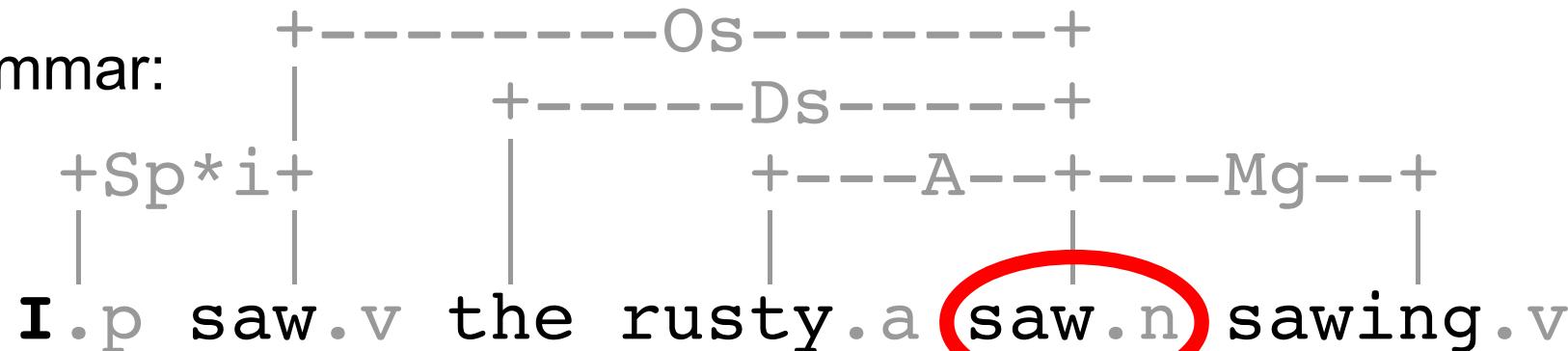
=> Horse

Unlabeled graph



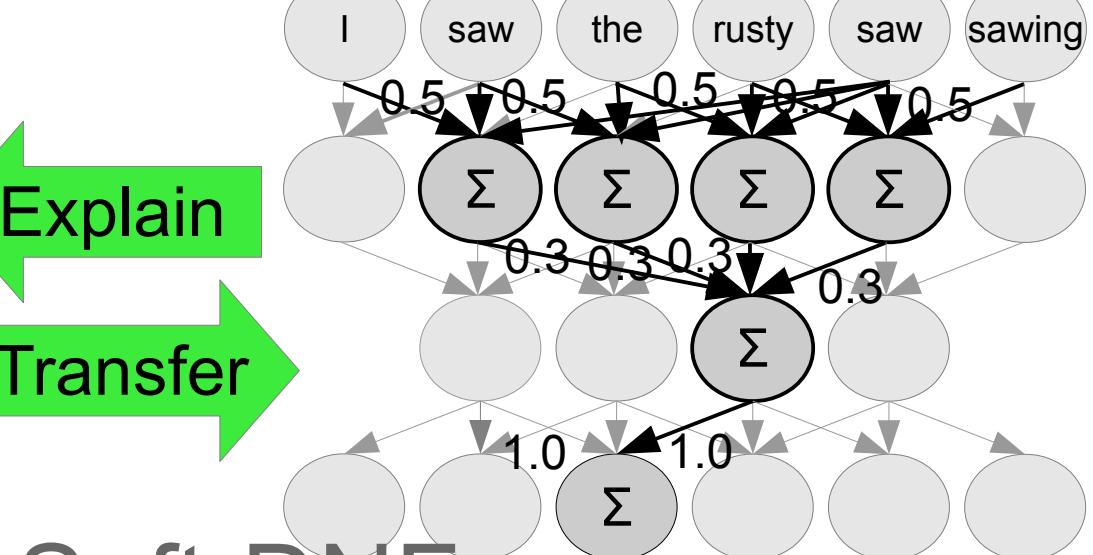
Bridging the Symbolic-Subsymbolic gap in NLP between distributed representations and formal grammars with ontologies

Link Grammar:



← Explain
Transfer →

Soft-DNF
Noun



Explainable AI (XAI) vs. Interpretable AI

XAI model output explanation techniques

“Dual” systems (like DNN + CBR)

Transformation to "soft" CNF/DNF rules (softmax, arg max)

XAI LIME

XAI SHAP

Life-long & Incremental Learning

(compression/forgetting–extraction–injection–extension)

Interpretable model representations

Deep Bayes

Deep Random Forest

Soft Decision Trees

Probabilistic/Fuzzy Logic

OpenCog/PLN

NARS

“Discovery”

Formal Concept Analysis (FCA)

New (and forgotten old) approaches

Convergence

Joining neural networks into cognitive architectures

Complex DNN Architectures

Attention-allocation networks

Contextual question answering and sentiment analysis

3D CNN for spatiotemporal predictions

Hybridization of neural networks with probabilistic programming

Integration of neural networks with semantic networks (“knowledge graphs”)

AGI

Narrow AGI (Ben Goertzel, SingularityNET)

Probabilistic programming

It is in the state of “neural networks” 20 years ago and may turn revolutionary
in just few years (Alexey Potapov, SingularityNET)

Agent Models

AIXI – universal compressor and predictor (Marcus Hutter, Arthur Franz)

Anokhin’s Theory of Functional Systems (TFS) extension (Evgenii Vityaev)

Reinforcement Learning based on "fluents" (state variables or atoms representing the states)

Ecosystem approach

No one knows how to make AGI (so "let all colors bloom")

Brain on itself is not the same (different brain regions have totally different “architectures”)

New (and forgotten old) approaches

Deep Learning for AGI

Demis Hassabis: "transfer learning is a key ... to general intelligence"

Yan Lecun: "learn models of the world"

Cognitive Pyramid:

Causality

Reinforcement-learning

Transfer-learning

Meta-learning (Learning to Learn)

DL

GANs

ML

...

World<->ControlNetwork<->ModelNetwork (*"Learn how to Learn"*)

A lot to study, still

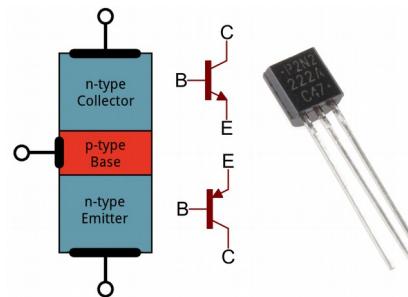
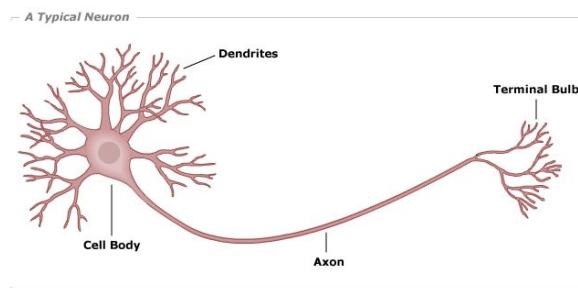
Dendrites/synapses branching

Holobionts - synergetically interacting societies

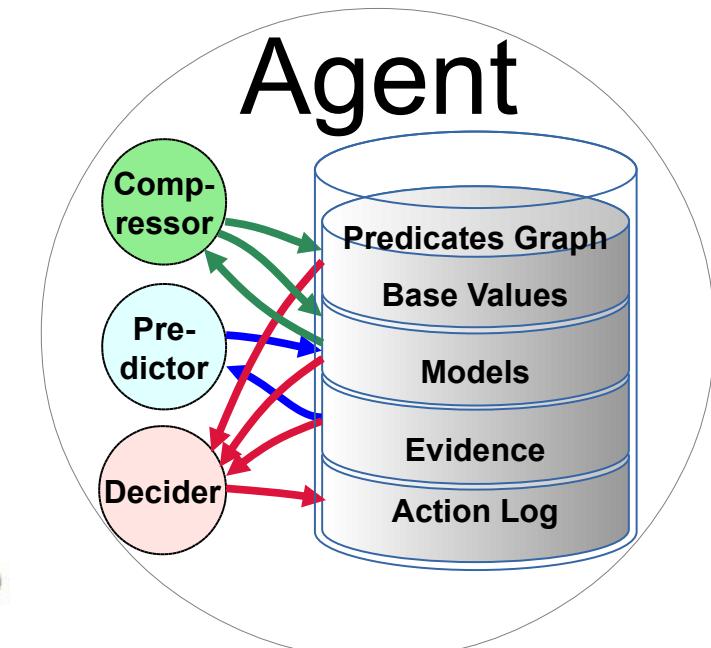
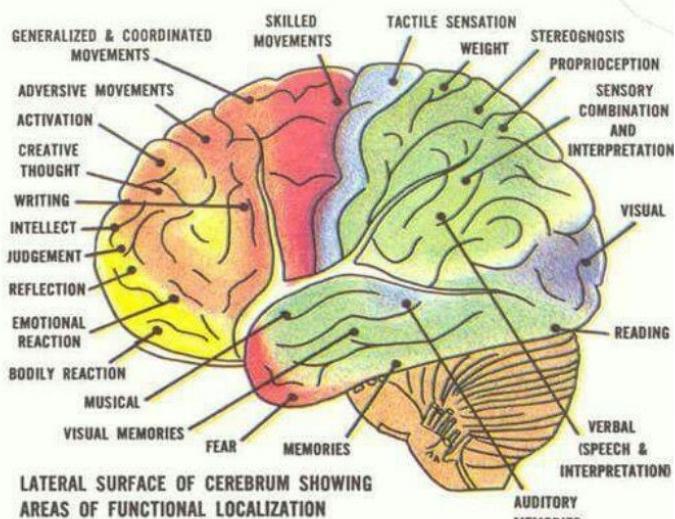
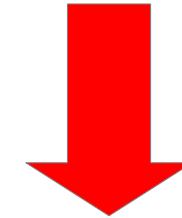
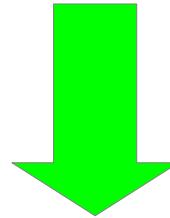
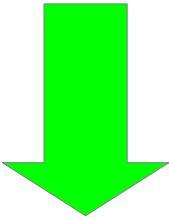
(matching studies by Jeff Hawkins,
who suggested the HTMs, preceding the DNNs)

Neuron Microtubules

What is the Atom suitable to build AGI?

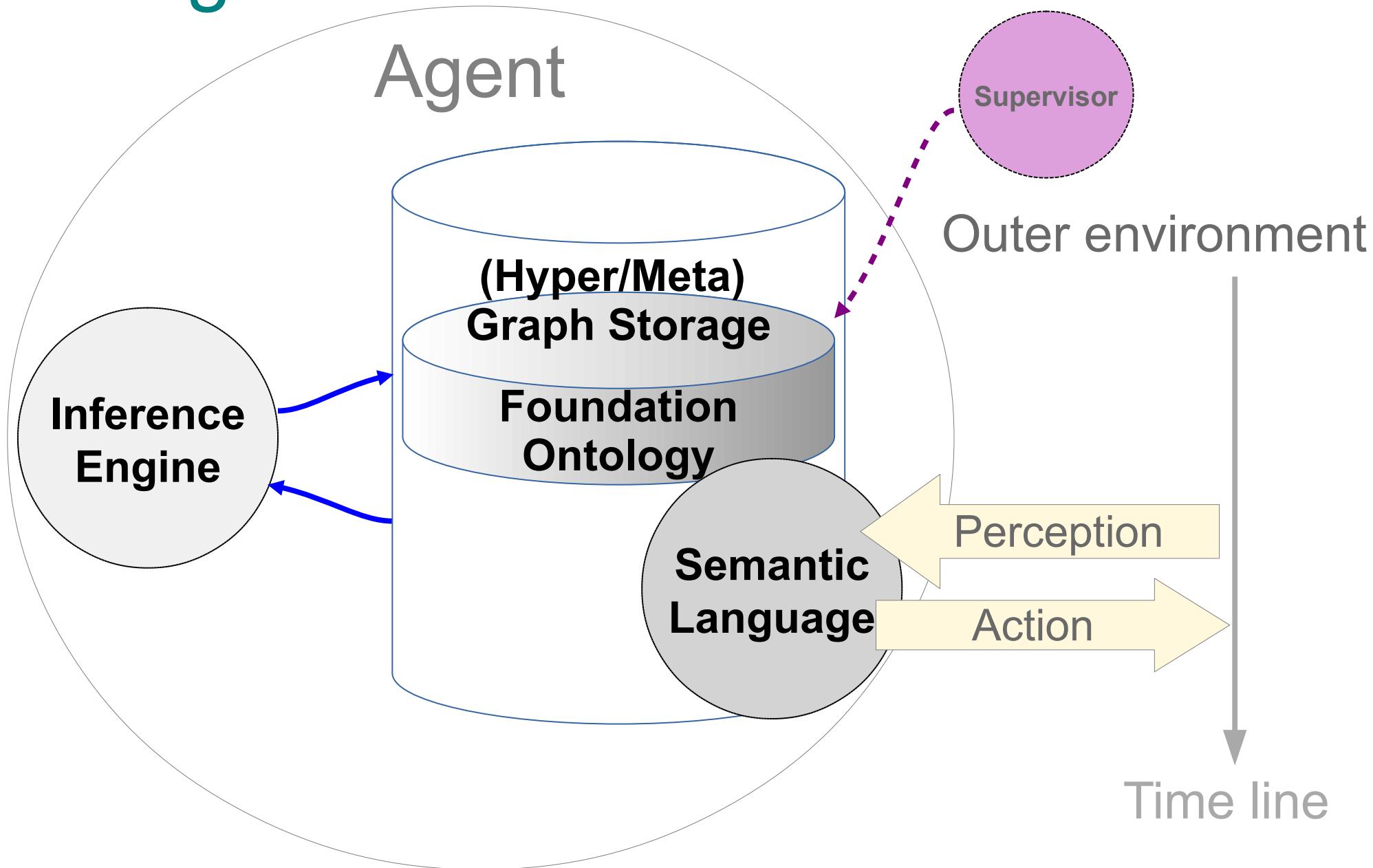


?



AGI Agent Cognitive Architecture

4 ingredients for “reasonable” AGI



Foundation Ontology

No-ontology

[Cyc Knowledge Base](#)

[Freebase/Google Knowledge Graph](#)

[OpenCog Atomspace](#)

[Webstructor/Aigents®](#)

Custom Domain

Graph Storage

Any RDBMS + time & triple indexing

Any “Triple Store” + time indexing

[TimeScale DB](#) + triple indexing

[OpenCog AtomSpace](#)

[Aigents® Temporal Graphs](#)

Semantic Language

RDF/OWL/Turtle/JSON-LD/SparQL

[Cycl](#) – Cyc Language (D.Lenat)

[ORL](#) (A.Kolonin, L.Kuzin)

[D0SL](#) (V.Gumiroy, D.Sviridenko)

[OpenCog Atomese](#) (B.Goertzel)

[Narsese](#) (P.Wang, P.Hammer)

[AL – Aigents® Language](#) (A.Kolonin)

[Premise](#) (M.Miller)

Inference Engine

Non-Axiomatic Reasoning System – [NARS](#) (P.Wang, et. al.)

Logical Prediction System – “[Discovery](#)” (E.Vityaev et.al.)

OpenCog Probabilistic Logic Network – [PLN](#) (B. Goertzel et. al.)

What is all you need?

	Inference Engine	Semantic Language	Graph Database	Foundation Ontology	License
OpenCog	Unified Rule Engine (URE)/ Probabilistic Logic Network (PLN)	Atomese	AtomSpace	AtomSpace Atom Types	GPL
Non-Axiomatic Reasoning System (NARS)	Non-Axiomatic Reasoning System (NARS)	Narsese	Internal In-memory	Ontology-agnostic?	MIT
Discovery + D0SL	Discovery	D0SL	Internal in-memory	D0SL	GPL + Commercial
Webstructor/ Aigents®	TBD	ORL, AL	Aigents Graphs	Aigents	MIT

Graph Storage for “Temporal Predicates”

Verb(Subject, Object)<Time>

RDBMS:

[Verb, Subject, Object, Time]
+ custom indexes on triple & time

Triple Stores (Neo4J, Grakn, etc.):
[Verb, Subject, Object](Time)
+ custom indexes on time

TimeScale DB:

[Verb, Subject, Object, Time]
+ custom indexes on triple

OpenCog AtomSpace:

custom representation & indexes

Aigents® Temporal Graphs:
Time([Verb, Subject, Object])



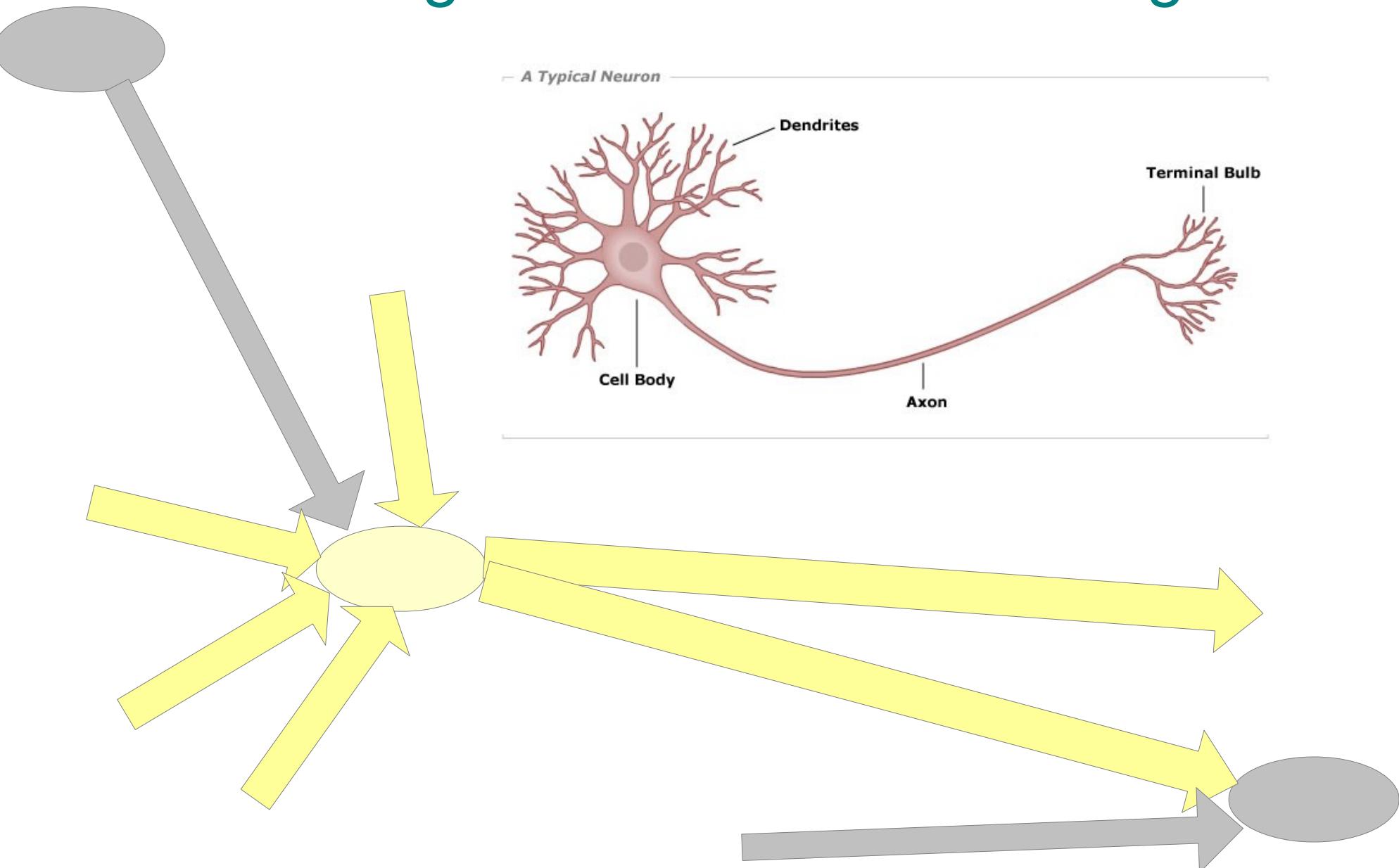
Anton Kolonin created a poll.

Moderator · September 20 ·

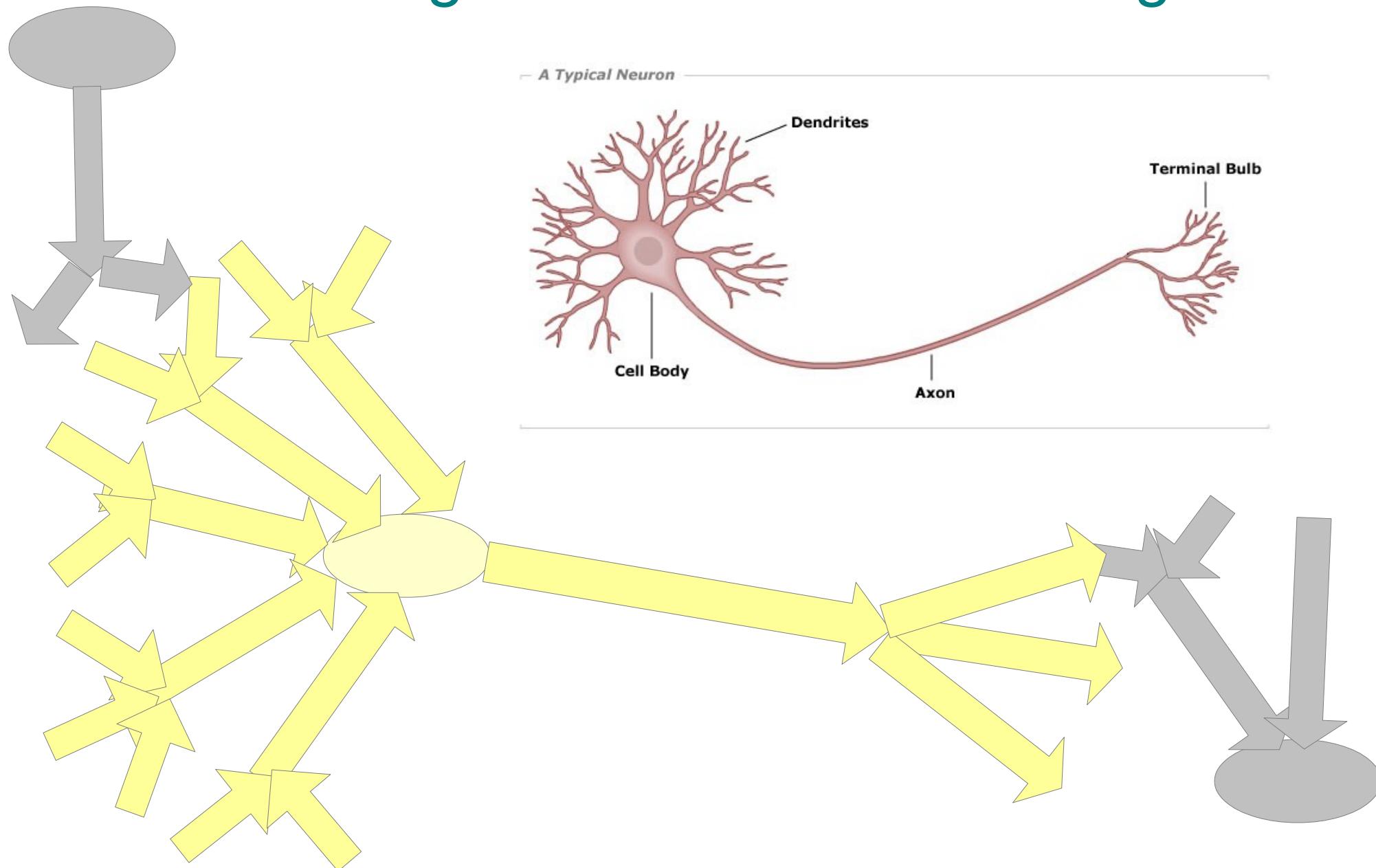
If you are doing causal/temporal inference (predictive analytics) in your cognitive architecture, where do you store the data?

- Added by you
Proprietary temporal graph DBX
10 votes
- Added by you
Aigents Temporal GraphsX
2 votes
- Added by Robert Fry
Somas. They store the actionable information for decisioning using Bayes' Theorem in log form where new information is additive....
1 vote
- Added by Mykola Rabchevskiy
Semantic Graph + Temporal Sequence...
1 vote
- Added by you
Timescale DB storing custom graphsX
1 vote
- Added by you
Grakn based solutionX
- Added by you
OpenCog AtomSpaceX
- Added by you
Neo4J based solutionX

Does Artificial Neuron Looks Like the Real One? Processing on Dendrites Branchings?

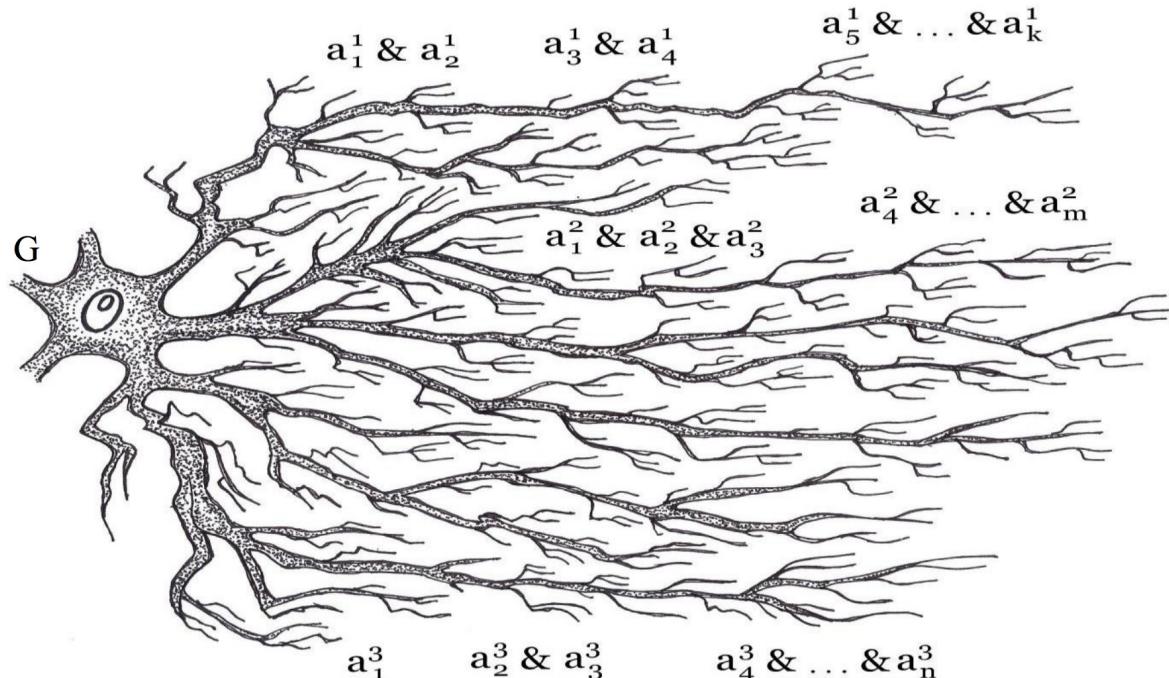


Does Artificial Neuron Looks Like the Real One? Processing on Dendrites Branchings?



Treating single neuron as hierarchy of predicates

Semantic probabilistic inference as a formal model of neuron



If G denotes a stimulus, on which the neuron responds unconditionally, then the stimuli arriving at the dendrites can establish conditional connections with excitation of the neuron G .

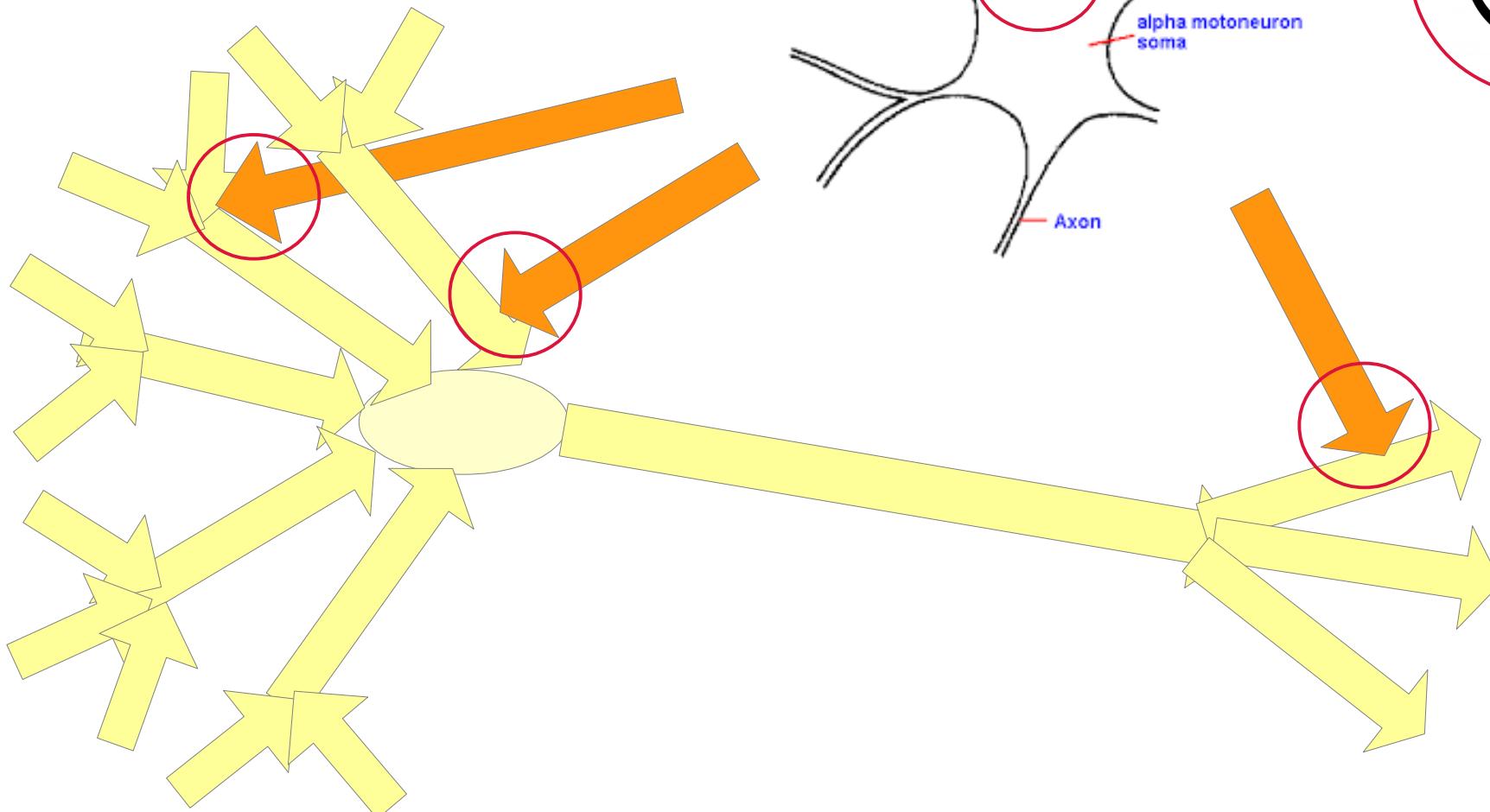
New stimulus are added to the rule only if they increase its conditional probability. This is a manifestation of the conditional connections closure at the level of a neuron, its plasticity.

Neurons respond faster to the most probable conditional connections and hence first of all on Maximum Specific Rules.

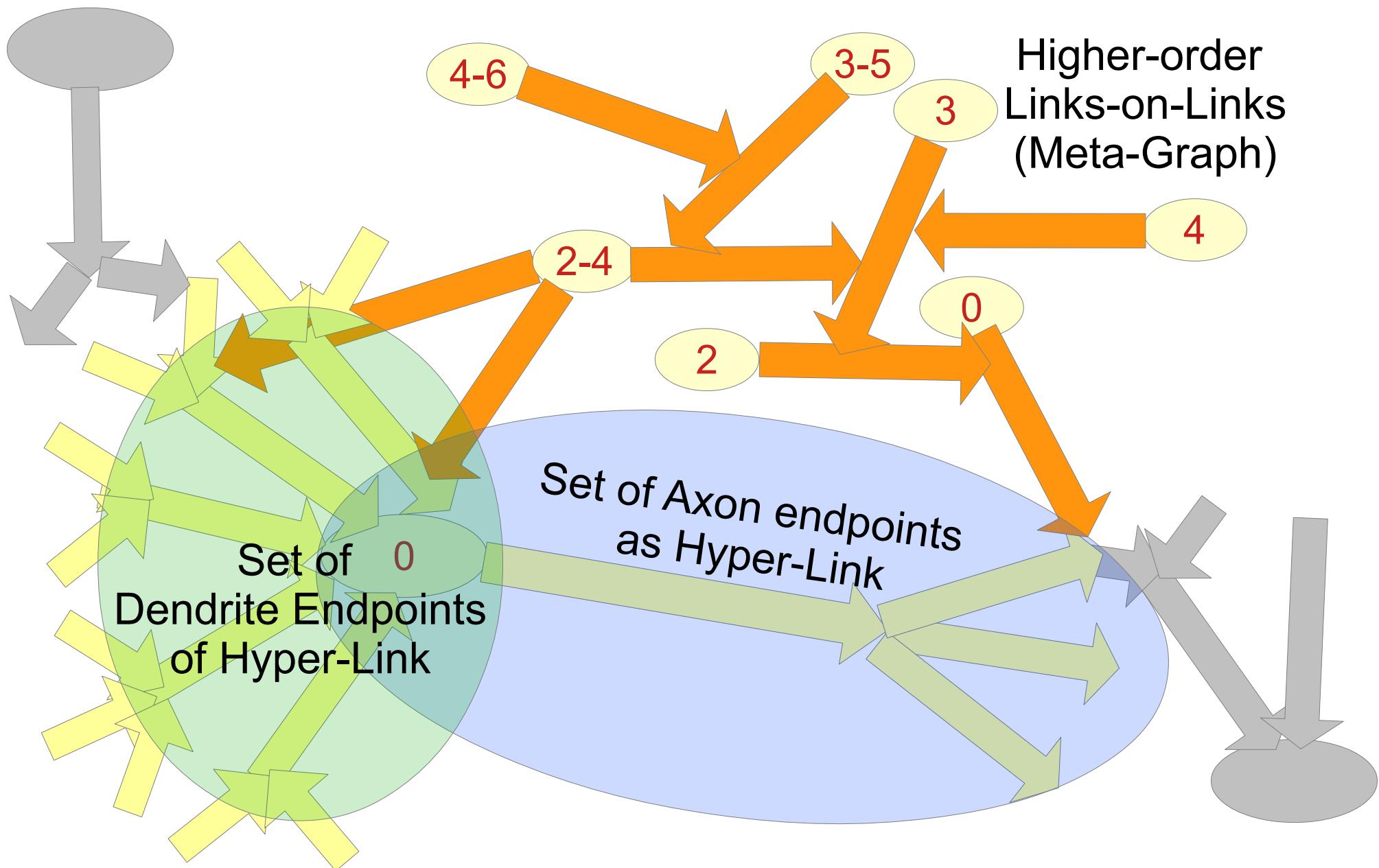
Vityaev E.E. A formal model of neuron that provides consistent predictions // Biologically Inspired Cognitive Architectures 2012. Proceedings of the Third Annual Meeting of the BICA Society. In Advances in Intelligent Systems and Computing, v.196, Springer. 2013, pp. 339-344.

<https://www.youtube.com/watch?v=fQ-bK17Y0Ak>

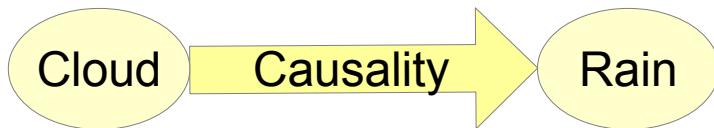
Does Artificial Neuron Looks Like the Real One? Synapses-on-Synapses?



True Connectome with Hyper-Meta Graphs



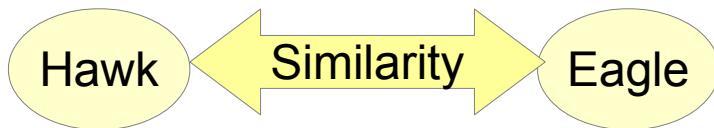
Ordered and Unordered Binary Links/Predicates and Hyper-Links



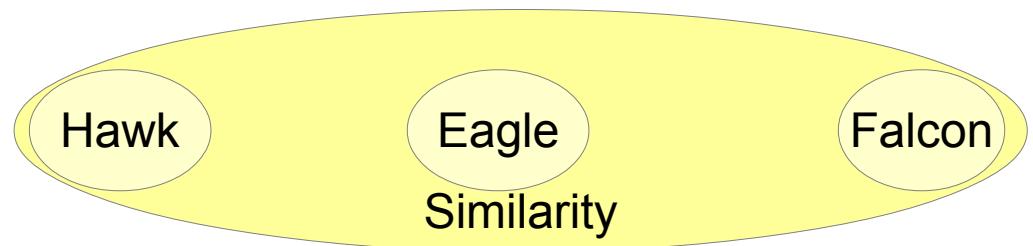
Ordered (directed) Link, arity = 2
Cloud is “source”
Rain is “target”
Real Link



Ordered (directed) Link, arity = 3
Cloud is “source”
Rain is “source” and “target”
Flood is “target”
Sequence or Series

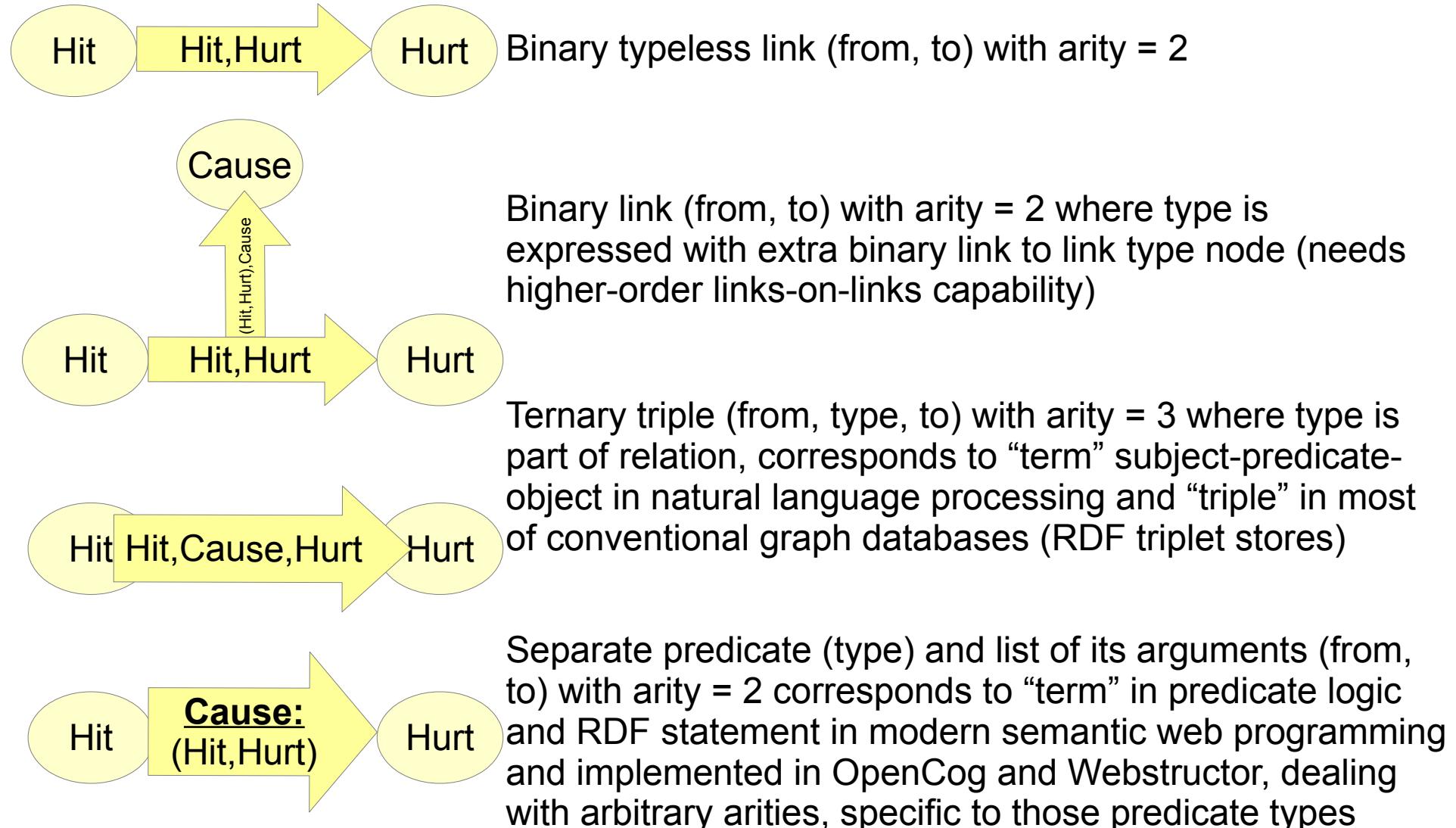


Unordered (undirected) Link, arity = 2
Just Pair

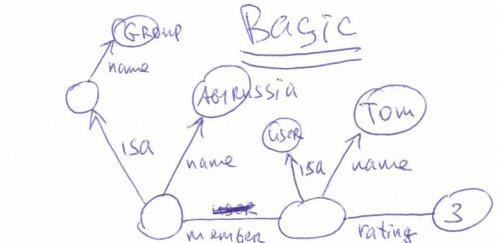


Unordered (undirected) Link, arity = 3
Set

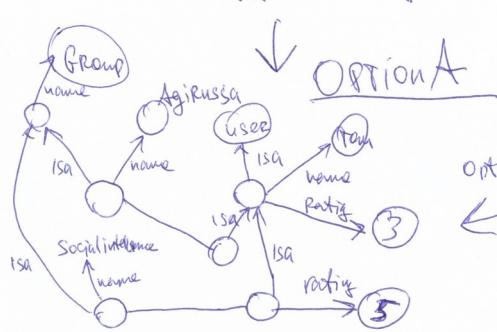
Typed/Labeled Links/Predicates vs. Arity



Typed predicates and design ambiguity vs. No-ontology with binary predicates only

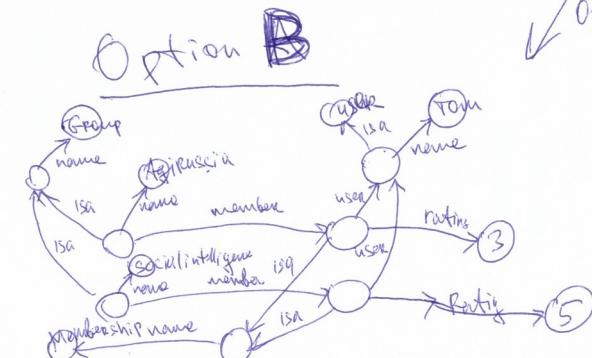


Tom is user, his name is Tom, he is a member of group AgIRussia.
Tom has Rating of 3.

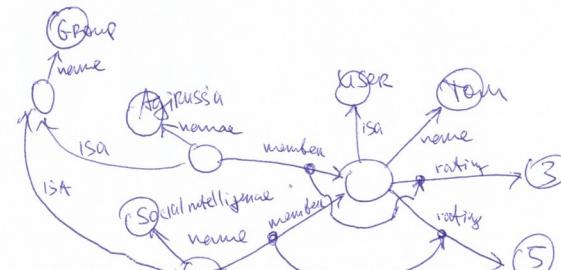


Option A

Tom has Rating of 3 in group AgIRussia.
Tom has Rating of 5 in group Social intelligence.

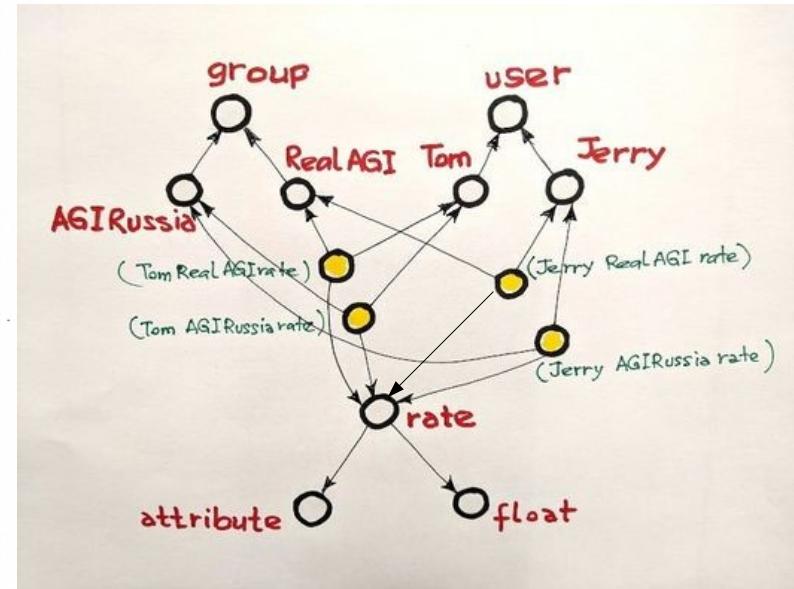
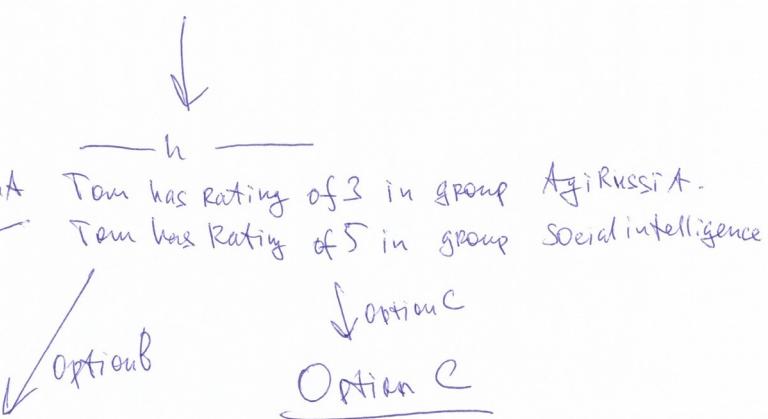


Option B



Option C

The problem – need to have certain kind of ternary relationships (typed links) to be specific to context, eg. “rating” property if a user in different groups may have different value. Redesign of the domain ontology to account for this has multiple ambiguous options involving need for meta-links (option C).



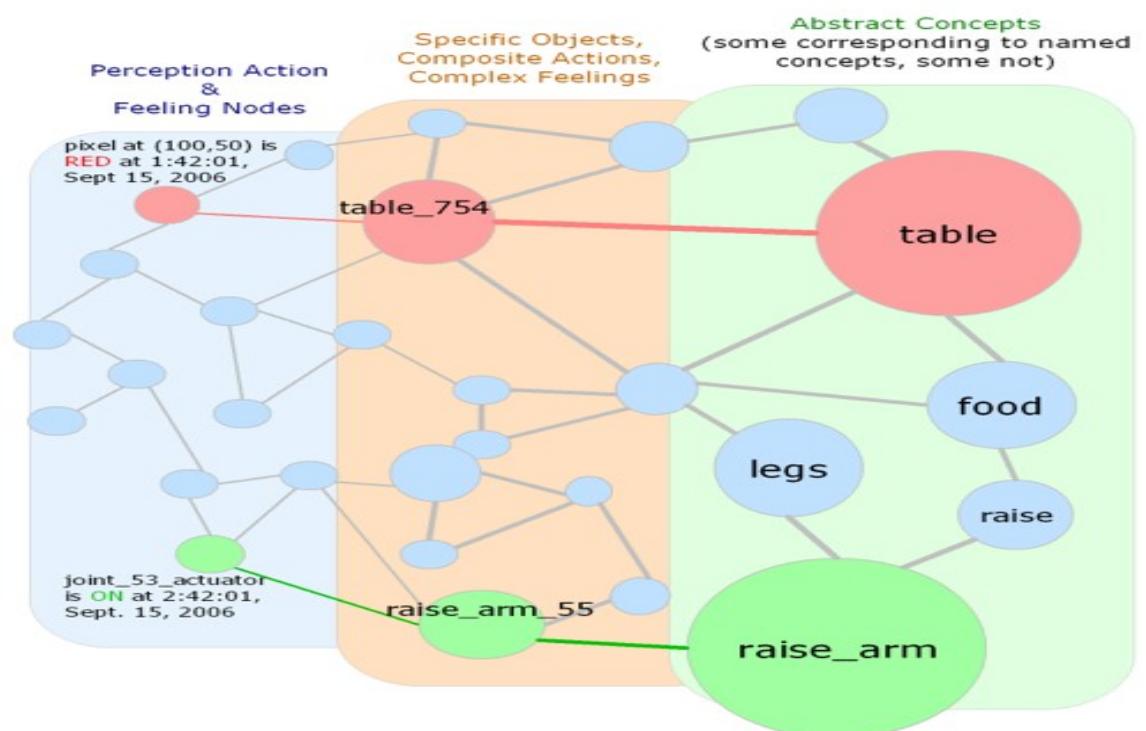
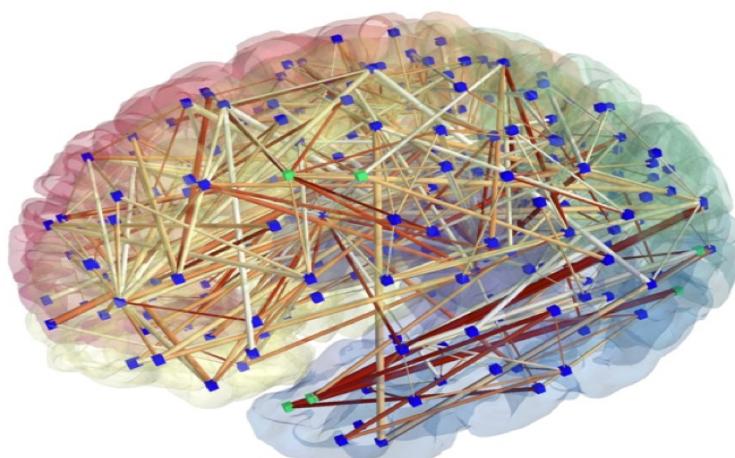
© Mykola Ryabchevsky, Gnosis Engineering
<http://www.ockhamstyle.com/>

The solution – don't have a “domain ontology” at all, let all links “binary” with implicit “is-a” type. Treat every meaningful relationship as an “unlabeled” node (yellow nodes above).

OpenCog's “AtomSpace”



Implements Generalized Hyper-graph and Meta-graph, so each directed/undirected link may link together any number of atoms, where atom could be either node (arity = 0) or any other link with any arity, including unordered N-ary links representing subgraphs as their elements.



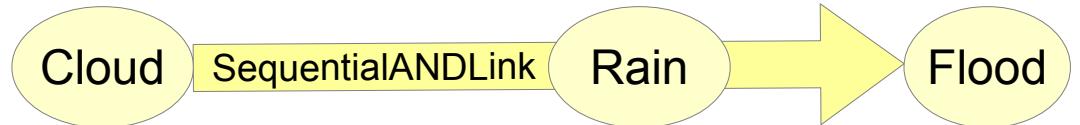
<https://github.com/opencog/atomspace>

https://github.com/opencog/atomspace/blob/master/opencog/atoms/atom_types/atom_types.script

Ordered (directed) and Unordered (undirected) Links



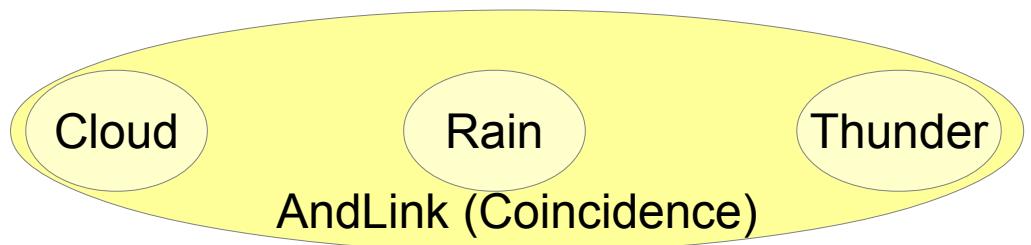
ImplicationLink
ConceptNode "Cloud"
ConceptNode "Rain"



SequentialANDLink
ConceptNode "Cloud"
ConceptNode "Rain"
ConceptNode "Flood"



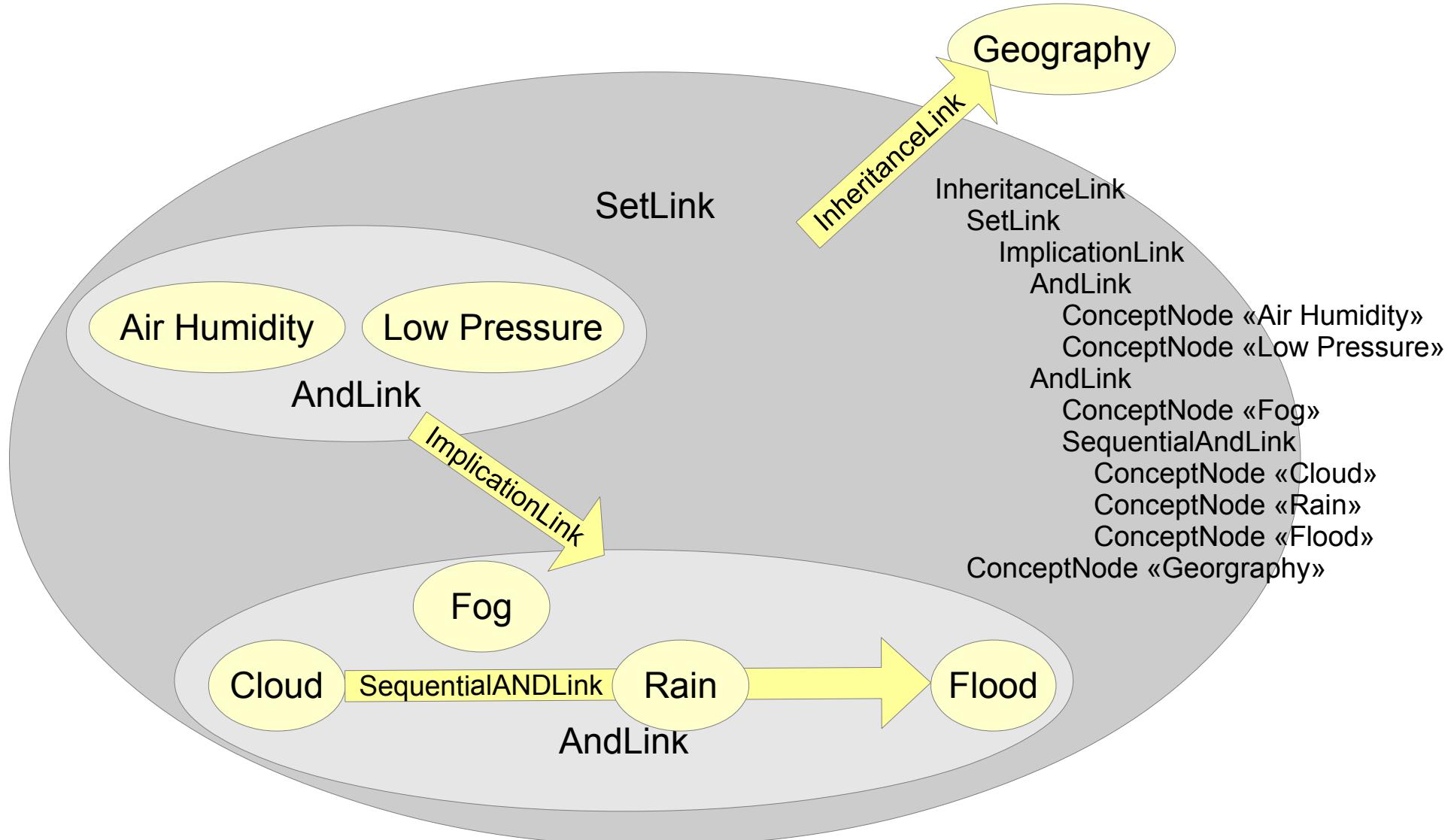
AndLink
ConceptNode "Cloud"
ConceptNode "Rain"



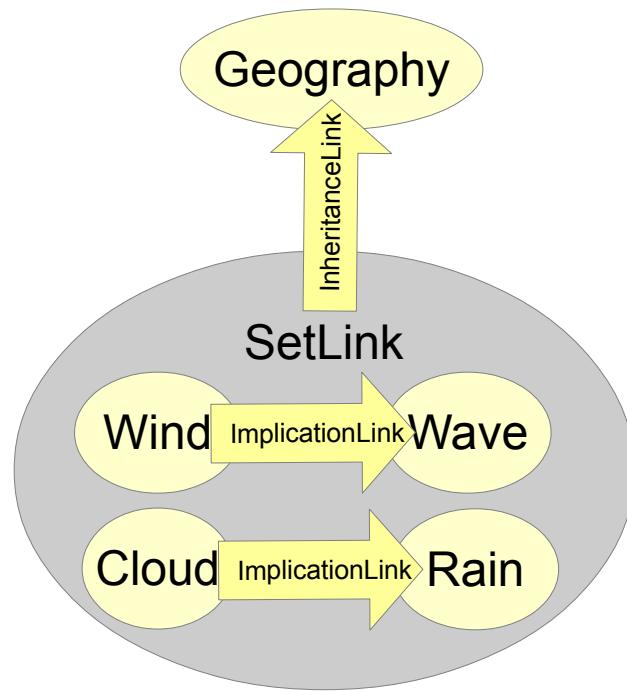
AndLink
ConceptNode "Cloud"
ConceptNode "Rain"
ConceptNode "Thunder"

expressed in Atomese language

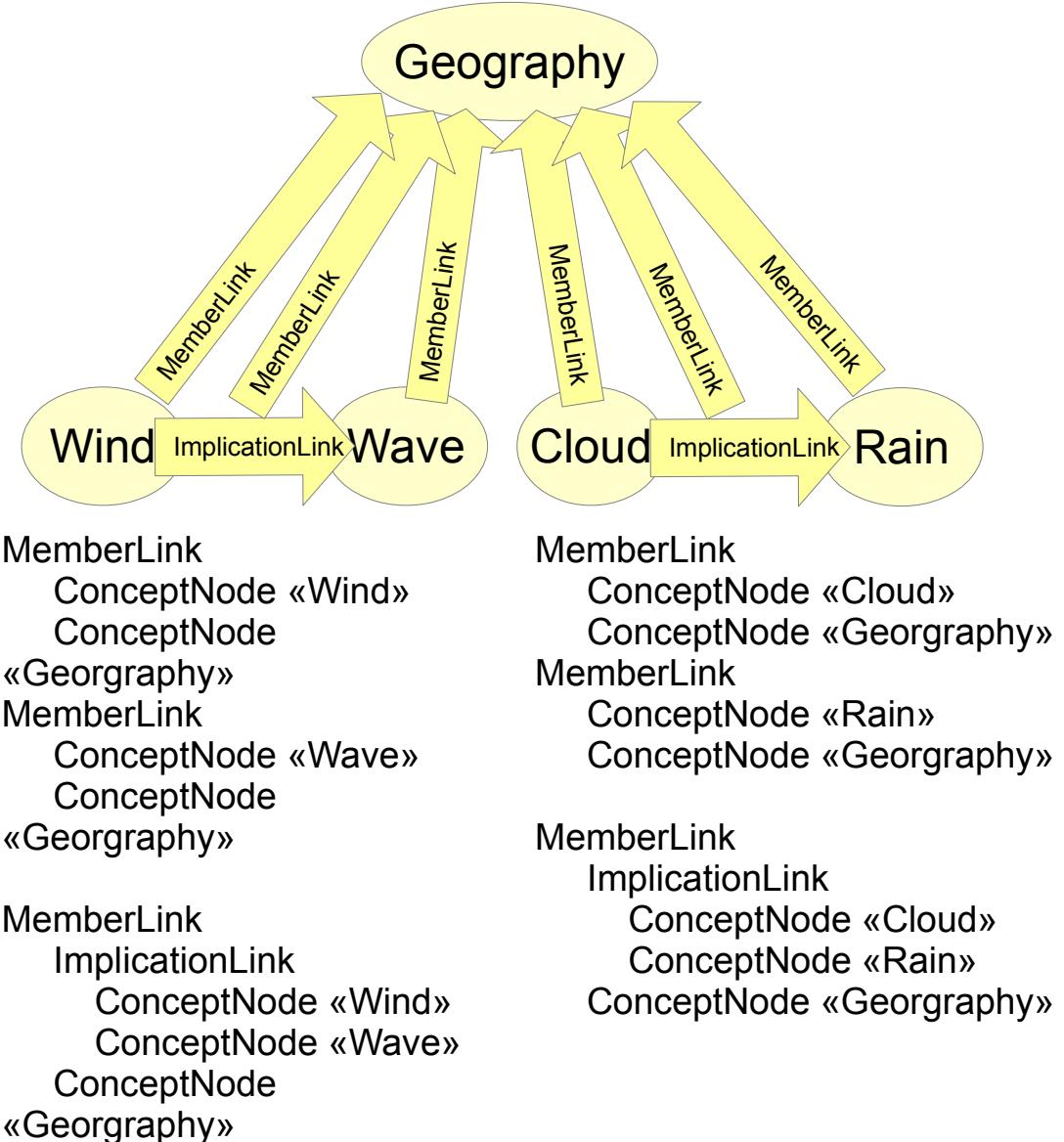
AtomSpace - Generalized (Link-as-Node) Hyper-Graph is a Meta-Graph (in Atomese)



AtomSpace - Meta-Graphs with Hyper-Graphs and Links-on-Links



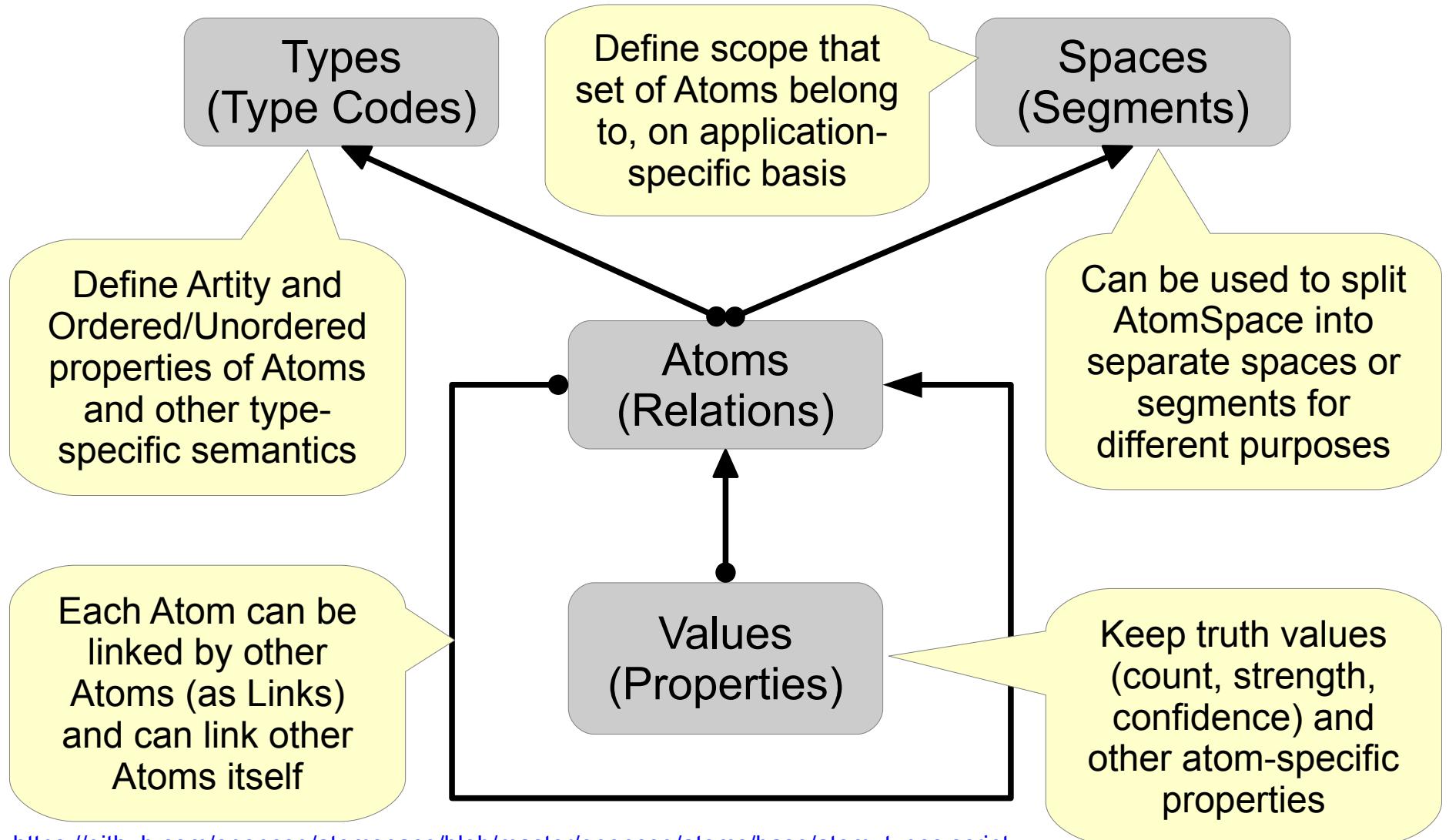
InheritanceLink
SetLink
ImplicationLink
ConceptNode «Wind»
ConceptNode «Wave»
ImplicationLink
ConceptNode «Cloud»
ConceptNode «Rain»
ConceptNode «Geography»



MemberLink
ConceptNode «Wind»
ConceptNode
«Geography»
MemberLink
ConceptNode «Wave»
ConceptNode
«Geography»
MemberLink
ImplicationLink
ConceptNode «Wind»
ConceptNode «Wave»
ConceptNode
«Geography»

MemberLink
ConceptNode «Cloud»
ConceptNode «Geography»
MemberLink
ConceptNode «Rain»
ConceptNode «Geography»
MemberLink
ImplicationLink
ConceptNode «Cloud»
ConceptNode «Rain»
ConceptNode «Geography»

OpenCog AtomSpace, what's inside

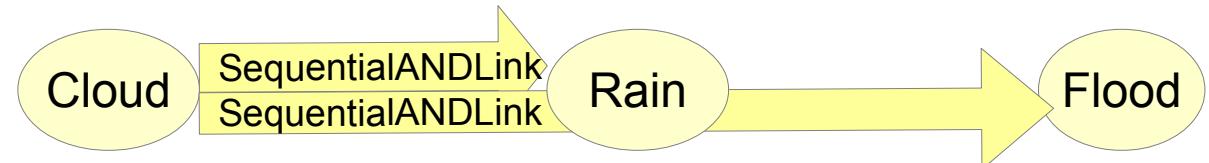


https://github.com/opencog/atomspace/blob/master/opencog/atoms/base/atom_types.script

OpenCog Atoms - example

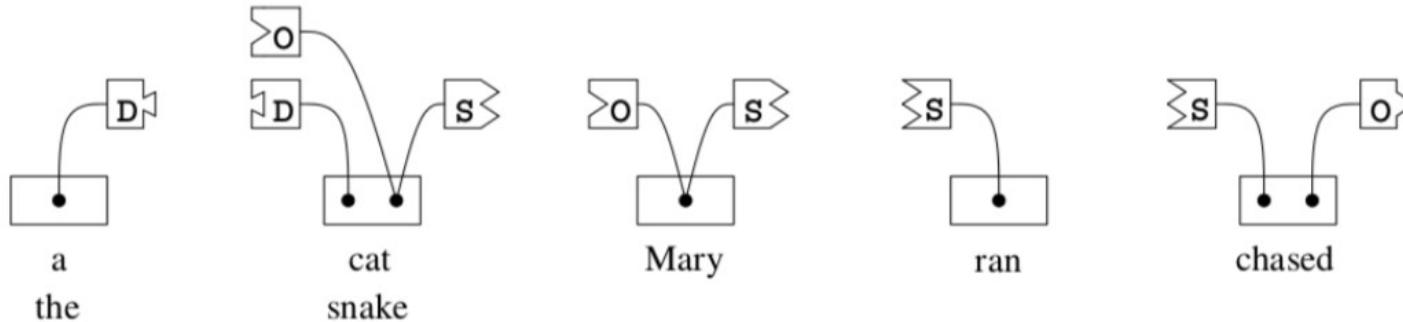
Id	Type	Space	Name (Label)	Level in Meta-Graph	Arity	Arguments	Truth Value: Count, Strength, Confidence
11	SequentialANDLink	5	-	2	2	13, 14	22 0.5 (22/44=50%) 1.0 («surely»)
12	SequentialANDLink	5	-	2	3	13, 14, 15	11 0.25 (11/44=25%) 0.5 («probably»)
13	ConceptNode	5	«Cloud»	0	0	-	44 1.0 1.0 («fact»)
14	ConceptNode	5	«Rain»	0	0	-	22 1.0 1.0 («fact»)
15	ConceptNode	5	«Flood»	0	0	-	11 1.0 0.5 («just news»)

Atom Type is used to infer if atom is link and if it is Ordered/directed or Unordered/undirected



https://github.com/opencog/atomspace/blob/master/opencog/atoms/base/atom_types.script

OpenCog Language Learning Domain (Link Grammar – Disjuncts & Connectors)

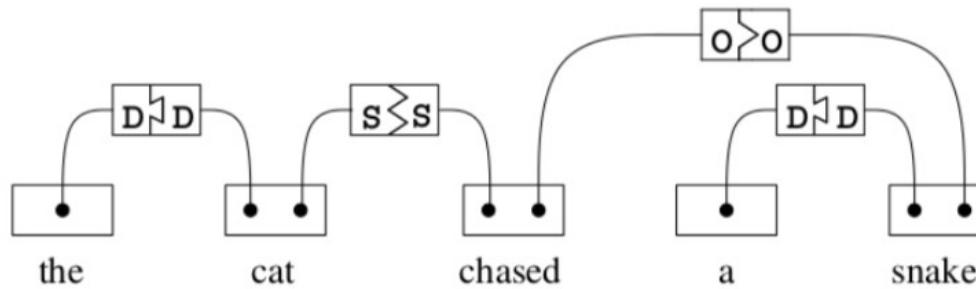


An illustration of Link Grammar connectors and disjuncts. The connectors are the jigsaw-puzzle-shaped pieces; connectors are allowed to connect only when the tabs fit together. A disjunct is the entire (ordered) set of connectors for a word. As lexical entries appearing in a dictionary, the above would be written as

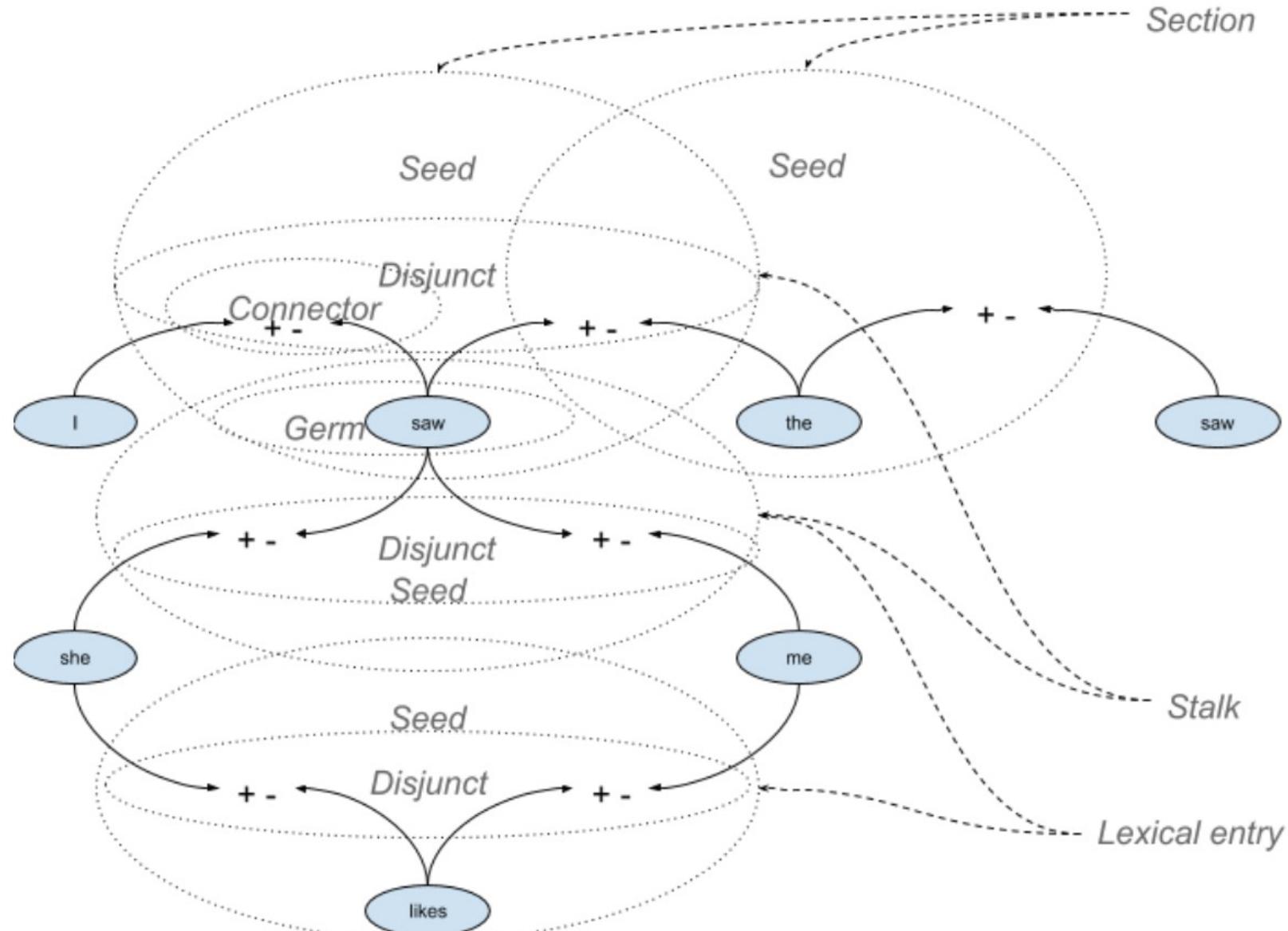
```
a the: D+;  
cat snake: D- & (S+ or O-);  
Mary: O- or S+;  
ran: S-;  
chased: S- & O+;
```

Note that although the symbols ‘‘&’’ and ‘‘or’’ are used to write down disjuncts, these are **not** Boolean operators, and do **not** form a Boolean algebra. They do form a non-symmetric compact closed monoidal algebra. The diagram below illustrates puzzle pieces, assembled to form a parse:

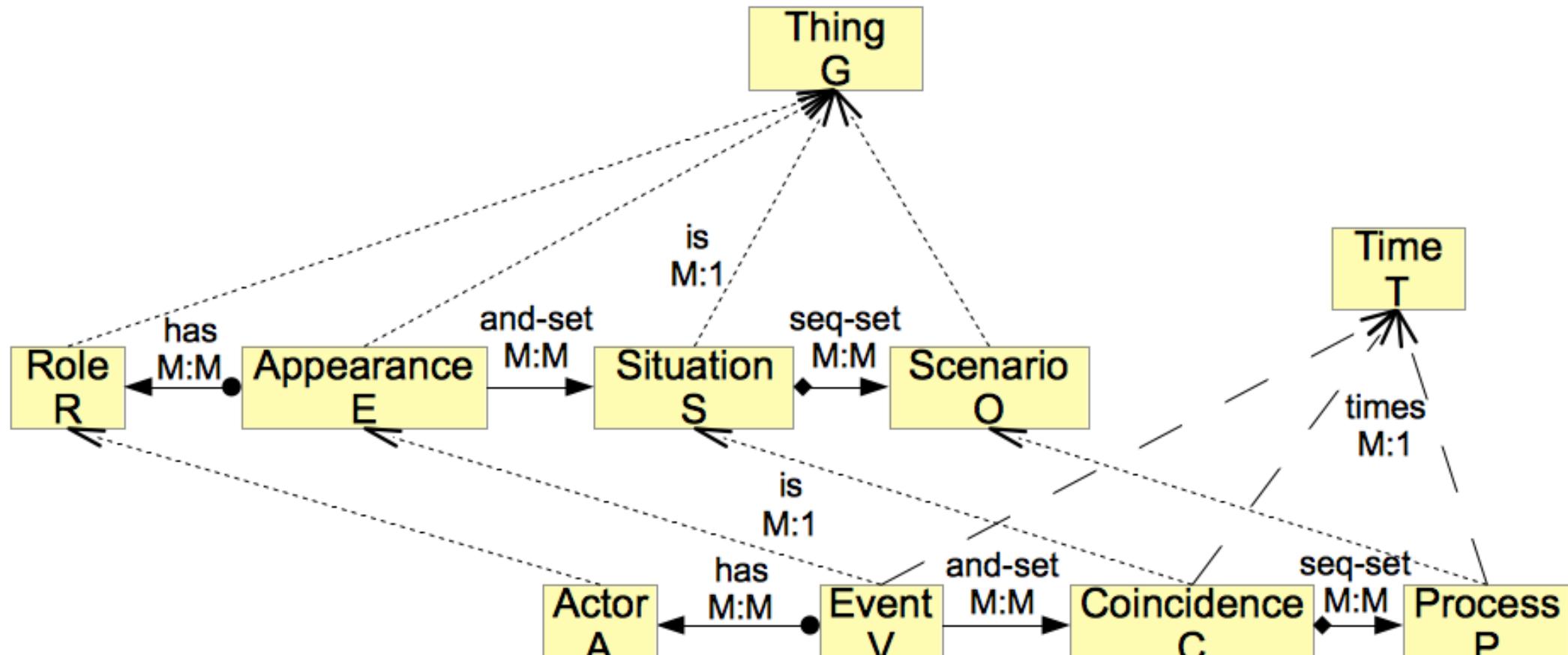
B. Goertzel,
L. Vepstas,
2014



OpenCog Language Learning Domain (Lexical Entries, Stalks, Sections)



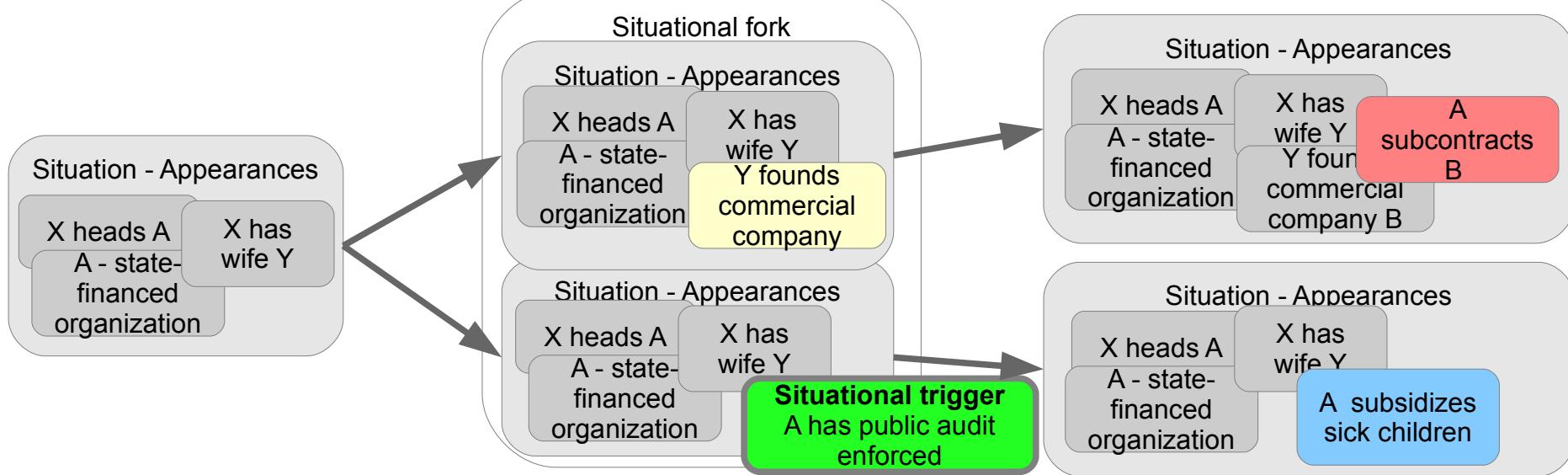
Scenarios and Processes - Unified Ontology



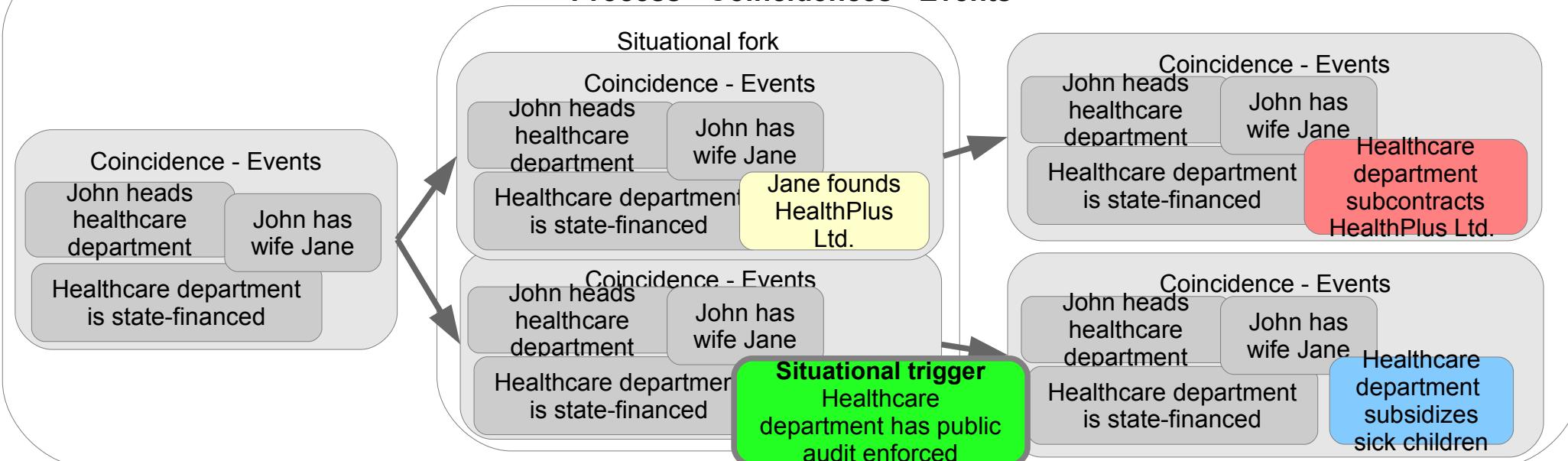
Data model in use with types of relationships indicated

Scenarios and Processes - Real Case

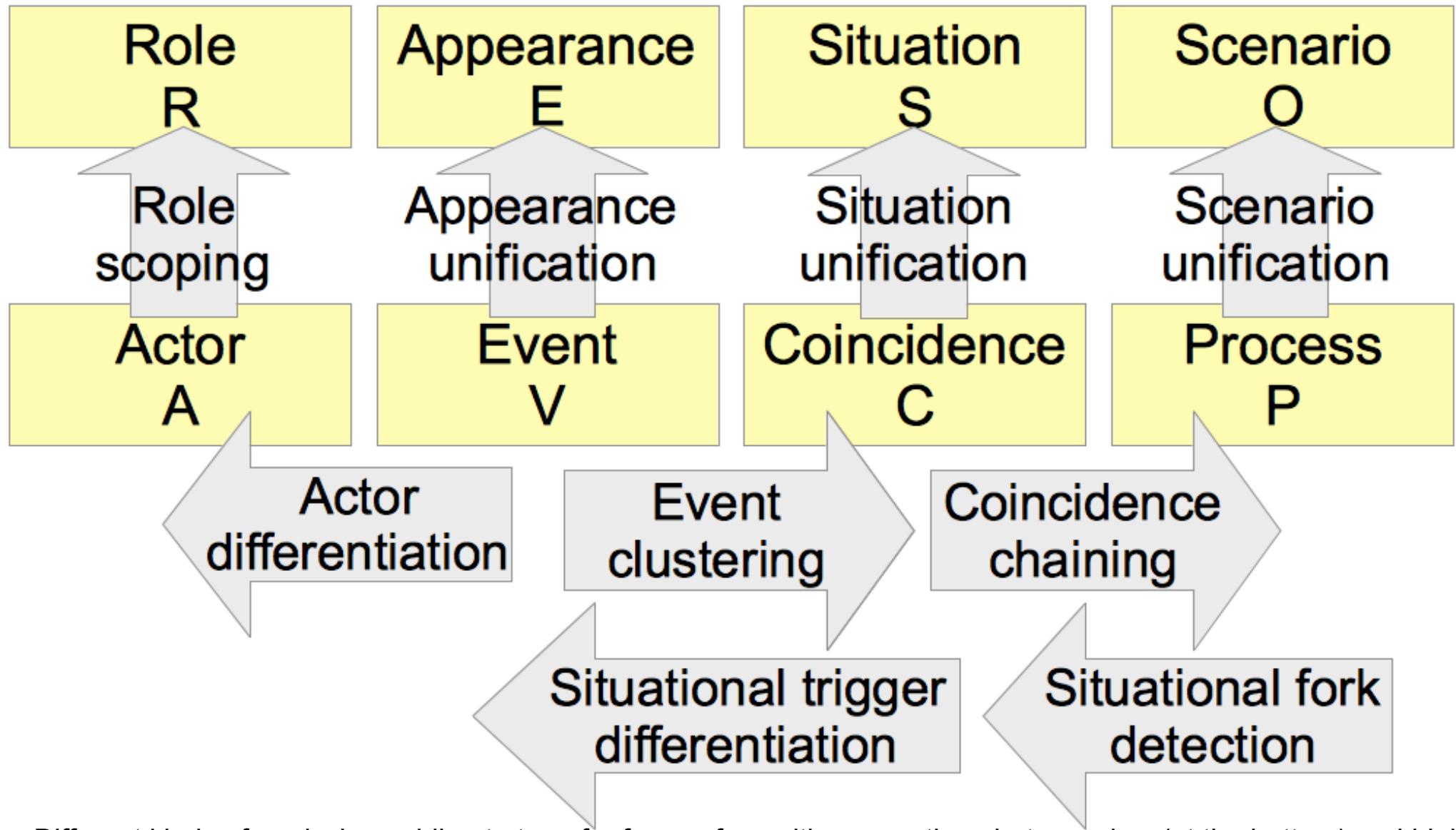
Scenario – Situations - Appearances



Process - Coincidences - Events



Scenarios and Processes - Cognitive Activities

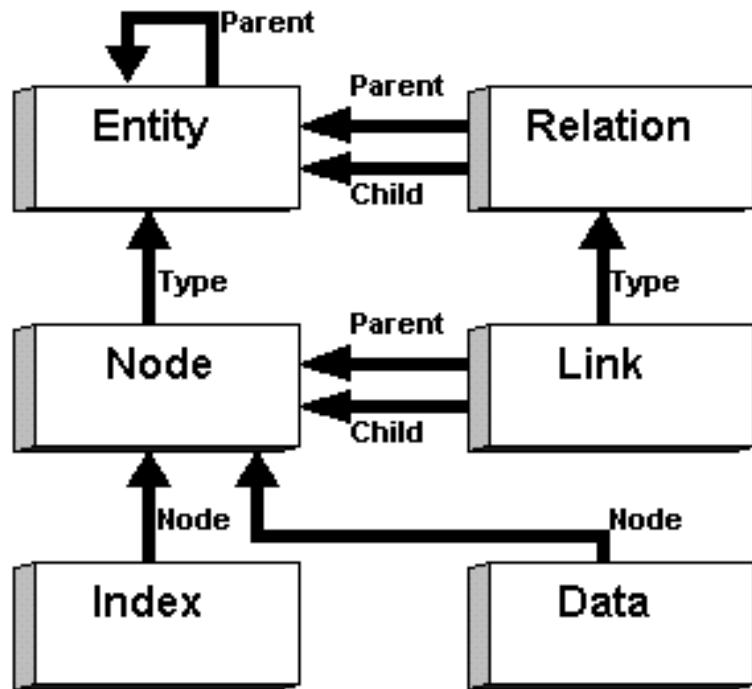


Different kinds of analysis enabling to transfer focus of cognitive operations between low (at the bottom) and high (at the top) abstraction levels and different degrees of aggregation – atomic (on the left) and ordered (on the right).

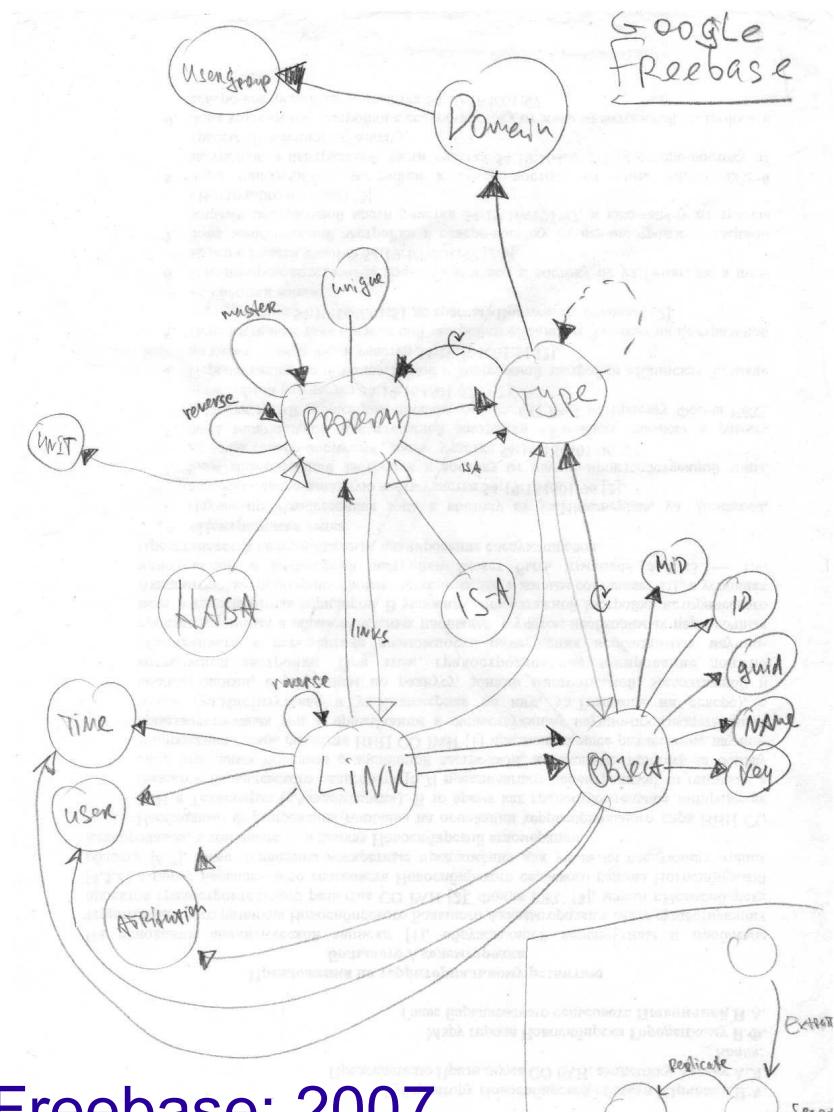
<https://arxiv.org/abs/1807.02072>

Foundation Ontologies - History

Database scheme view



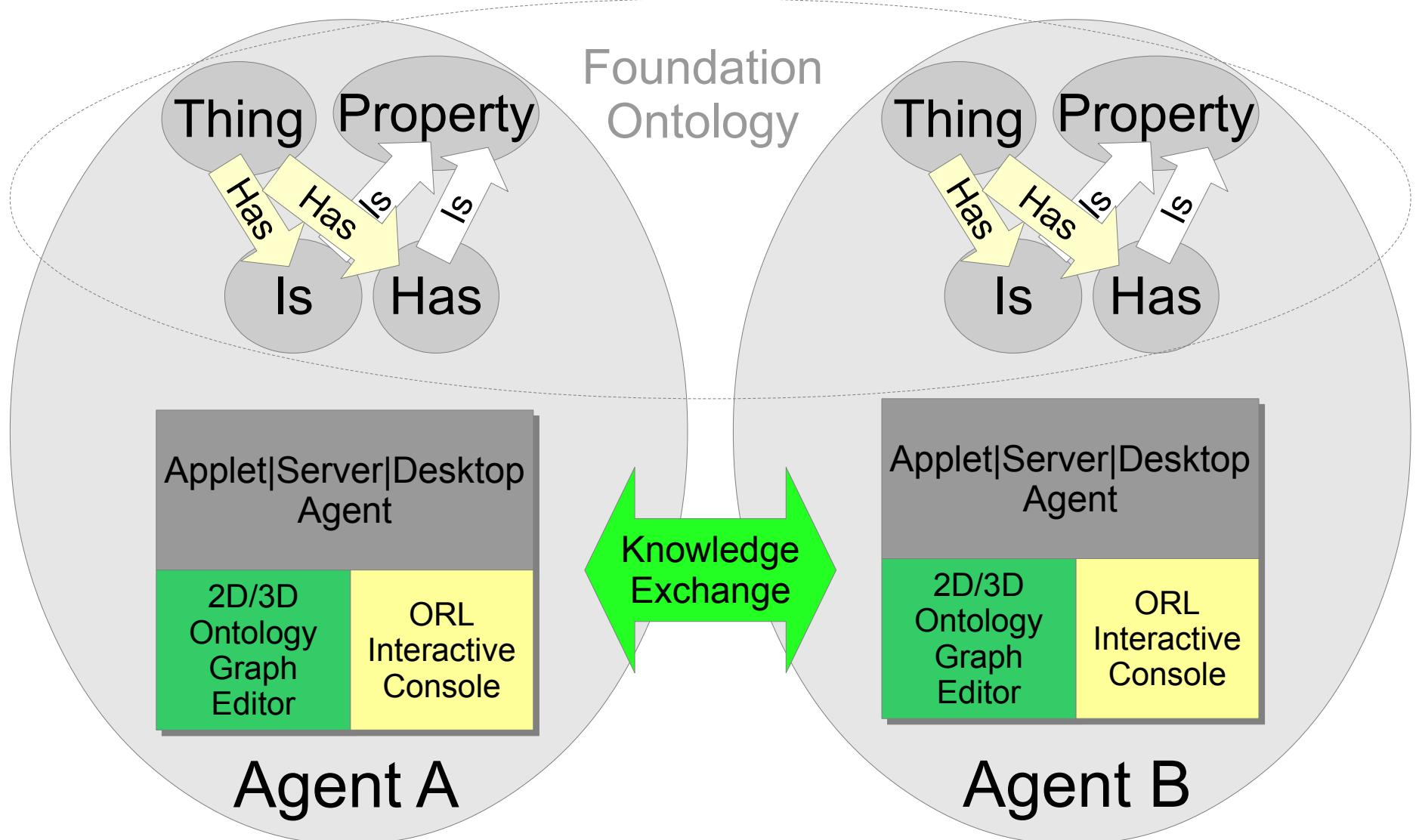
Data4: 1995



Freebase: 2007
Knowledge Graph: 2013

Distributed Knowledge Editor

Webstructor: 2001-2006



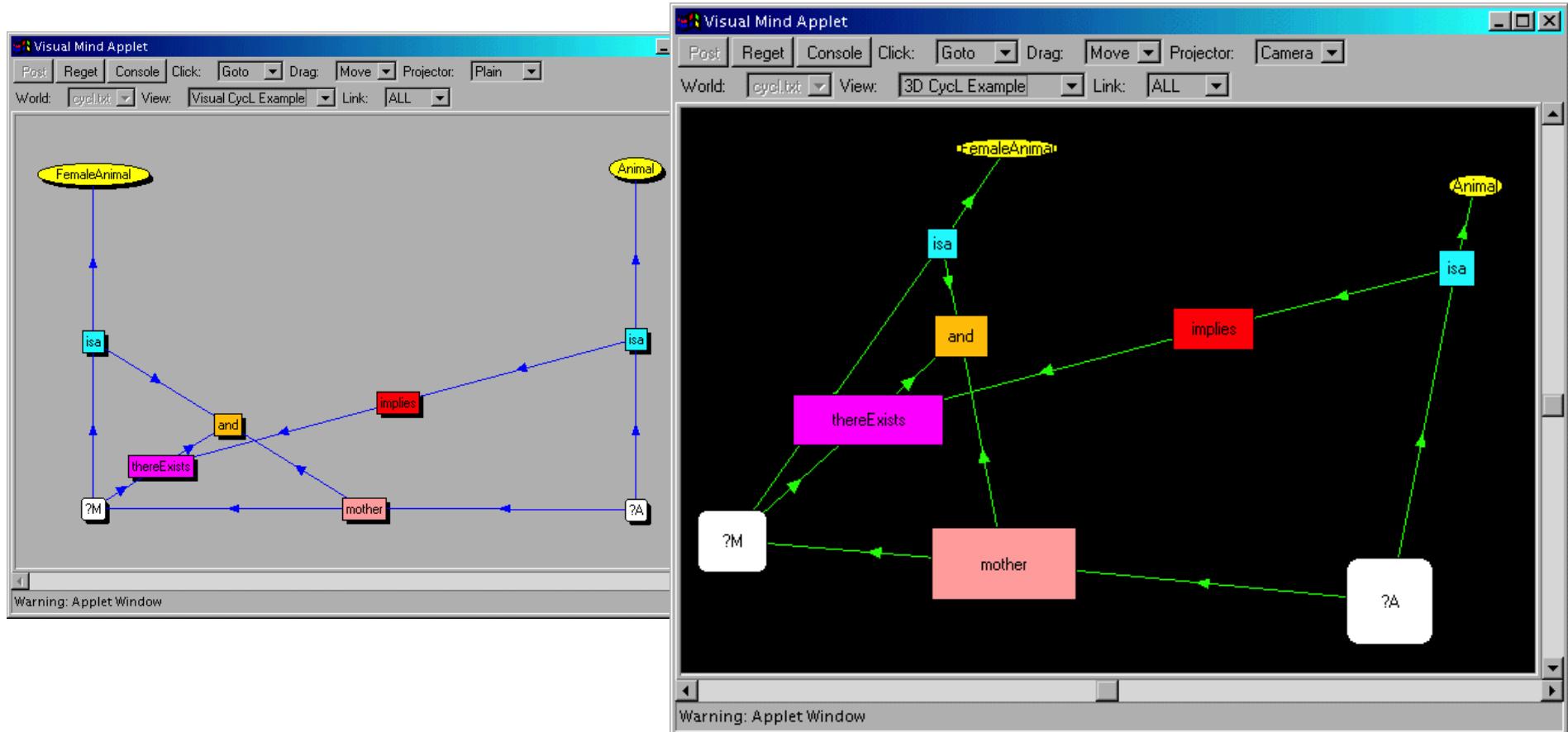
Semantic Modeling of Business Processes

Object Relational Language (ORL)

English	ORL
Here are the items A, B and C where A has properties X and Y while B and C are in relationship Z.	ITEM A,B,C;; A HAS (X), (Y);; B Z(C);;
In order to reach goal 1 one needs condition 2 and 3 to be held true while 2 can be true only if condition 4 happens.	CONDITION C2,C3,C4;; GOAL G1 REQUIRES (C2),(C3);; CONDITION(C2) REQUIRES (C4);;
Each morning need to perform this and that in order, having such and such done at once next.	PROCESS TIME "8:00"; REPEAT (DAILY); ORDER DO THIS, DO THAT;, FORK DO SUCH, DO SUCH;;;
What is that my stuff you mentioned yesterday or the day before?	STUFF(OWNER (ME), UPDATE (AUTHOR (YOU), {TIME "2013-03-22", TIME "2013-03-21"}).TELL;
What were the relationships between P and Q last year?	PROPERTY(OWNER (P), THING (Q), TIME "2012").TELL;
Let me know once they roll out next version of the product.	DO EMAIL TO "me@at.org";; WHEN PRODUCT(VENDOR (THEY)).VERSION CHANGE;;

Webstructor: Distributed Knowledge Editor

Visual 2D/3D editor of logical assertions (e.g. CycL)

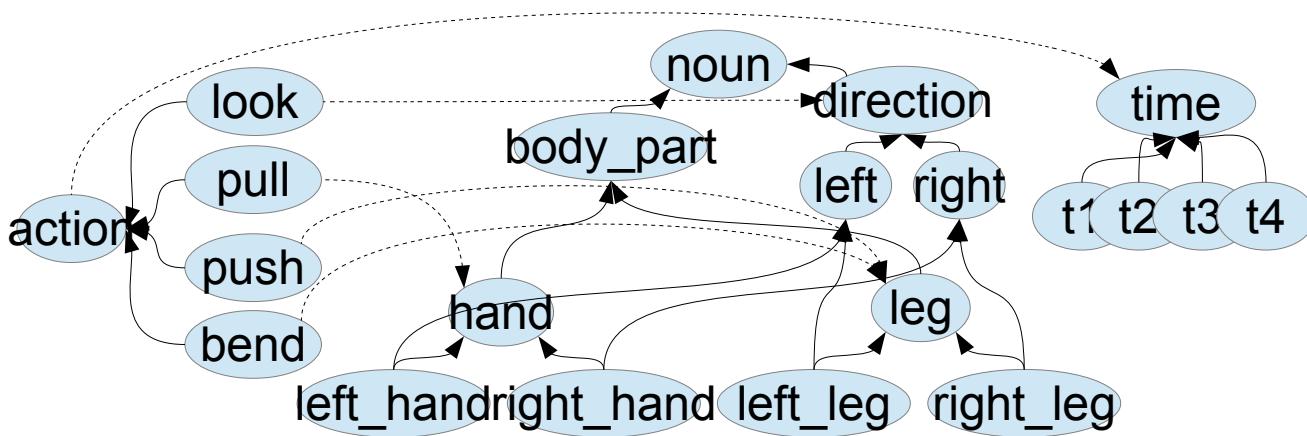


(implies (isa ?A Animal) (thereExists ?M (and (mother ?A ?M) (isa ?M FemaleAnimal))))
=

Mother of an animal is a female animal.

<http://agents.com/papers/2019/ontologies-language-agents-2019.pdf>

Semantic modeling using Premise language



push(right_leg, t1);
push(left_leg, t1);
pull(right_hand, t1). push(left_leg, t2);
pull(right_hand, t2);
pull(left_hand, t2); look(right,t3);
pull(left_hand,t3);
greater(t2,t1); greater(t3,t2);
greater(t2,t1);

pull(right_hand,t4);
bend(right_leg,t4);
bend(left_leg,t4);
greater(t4,t3).

```
;;; Agents.pr

(module Agents

  (enumeration Action look pull push bend)

  (enumeration BodyPart hand leg)

  (enumeration Direction left right)

  (enumeration Hand left_hand right_hand)

  (enumeration Leg left_leg right_leg)

  (enumeration Time t1 t2 t3 t4)

  (relation Instance
    :Category
    :Instance
  )

  (new Instance :Category left :Instance left_hand)
  (new Instance :Category left :Instance left_leg)
  (new Instance :Category right :Instance right_hand)
  (new Instance :Category right :Instance right_leg)

  (relation Statement
    :Verb
    :Object
    :Adverb
  )

  (relation Greater :More :Less)
  (new Statement :Verb push :Object right_leg :Adverb t1)
  (new Statement :Verb push :Object left_leg :Adverb t1)
  (new Statement :Verb pull :Object right_hand :Adverb t1)

  (new Statement :Verb push :Object left_leg :Adverb t2)
  (new Statement :Verb pull :Object right_hand :Adverb t2)
  (new Statement :Verb pull :Object left_hand :Adverb t2)
  (new Greater :More t2 :Less t1)

  (new Statement :Verb look :Object right :Adverb t3)
  (new Statement :Verb pull :Object left_hand :Adverb t3)
  (new Greater :More t3 :Less t2)

  (new Statement :Verb pull :Object right_hand :Adverb t4)
  (new Statement :Verb bend :Object right_leg :Adverb t4)
  (new Statement :Verb bend :Object left_leg :Adverb t4)
  (new Greater :More t4 :Less t3)

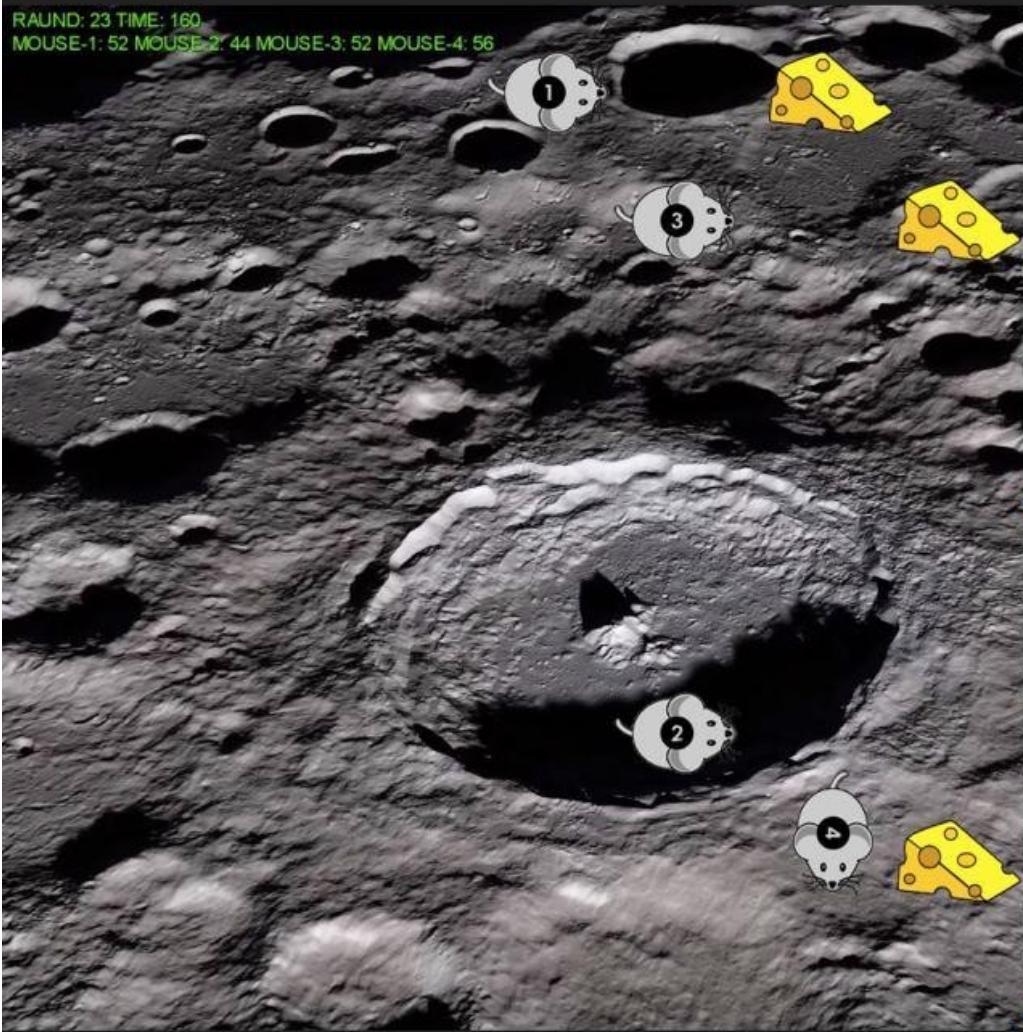
)
```

The Premise Reference by Michael S. P. Miller
(ISBN 978-1795680127)

<https://www.amazon.com/Premise-Language-Building-Minds-Patterns/dp/1983178136>

Reinforcement Learning for a Goal-Driven Behavior as a Probabilistic Semantic Program (D0SL)

RAUND: 23 TIME: 160
MOUSE-1: 52 MOUSE-2: 44 MOUSE-3: 52 MOUSE-4: 56



Semantic rules from round 22

Updated every three rounds

goal < GOAL_CLOSER >

rule < GOAL_SOMEWHERE_AHEAD > p=0.9999942252462992 a=move

goal < GOAL_SOMEWHERE_AHEAD >

rule < GOAL_LEFT GOAL_SOMEWHERE_LEFT > p=1 a=turn left

goal < GOAL_LEFT GOAL_SOMEWHERE_LEFT >

rule < GOAL_AHEAD GOAL_SOMEWHERE_AHEAD > p=1 a=turn right

rule < GOAL_SOMEWHERE_RIGHT > p=1 a=turn right

goal < GOAL_SOMEWHERE_RIGHT >

rule < GOAL_SOMEWHERE_AHEAD_RIGHT > p=0.9999939256444009 a=move

goal < GOAL_SOMEWHERE_AHEAD_RIGHT >

rule < OBSTACLE_RIGHT GOAL_SOMEWHERE_AHEAD_LEFT > p=1 a=turn left

rule < GOAL_SOMEWHERE_BEHIND_RIGHT > p=1 a=turn right

goal < GOAL_SOMEWHERE_BEHIND_RIGHT >

rule < OBSTACLE_LEFT GOAL_SOMEWHERE_AHEAD_RIGHT > p=1 a=turn left

[xai] goal: < GOAL_SOMEWHERE_AHEAD >

[xai] rule: < GOAL_SOMEWHERE_RIGHT > p=1 --> turn right

[xai] goal: < GOAL_CLOSER >

[xai] rule: < GOAL_SOMEWHERE_AHEAD > p=0.9999951877009052 --> move

[xai] goal: < GOAL_SOMEWHERE_AHEAD >

[xai] rule: < GOAL_SOMEWHERE_RIGHT > p=1 --> turn right

[xai] goal: < GOAL_CLOSER >

[xai] rule: < GOAL_SOMEWHERE_AHEAD > p=0.9999959897476932 --> move

[xai] goal: < GOAL_CLOSER >

[xai] rule: < GOAL_SOMEWHERE_AHEAD > p=0.9999966581209827 --> move

[xai] goal: < GOAL_SOMEWHERE_RIGHT >

[xai] rule: < GOAL_SOMEWHERE_AHEAD_RIGHT > p=0.9999970706158293 --> move

[xai] goal: < GOAL_SOMEWHERE_AHEAD >

[xai] rule: < GOAL_SOMEWHERE_RIGHT > p=1 --> turn right

[xai] goal: < GOAL_CLOSER >

[xai] rule: < GOAL_SOMEWHERE_AHEAD > p=0.9999972150993854 --> move

© 2019 E.Vityaev, V.Gumirov, P.Matukov

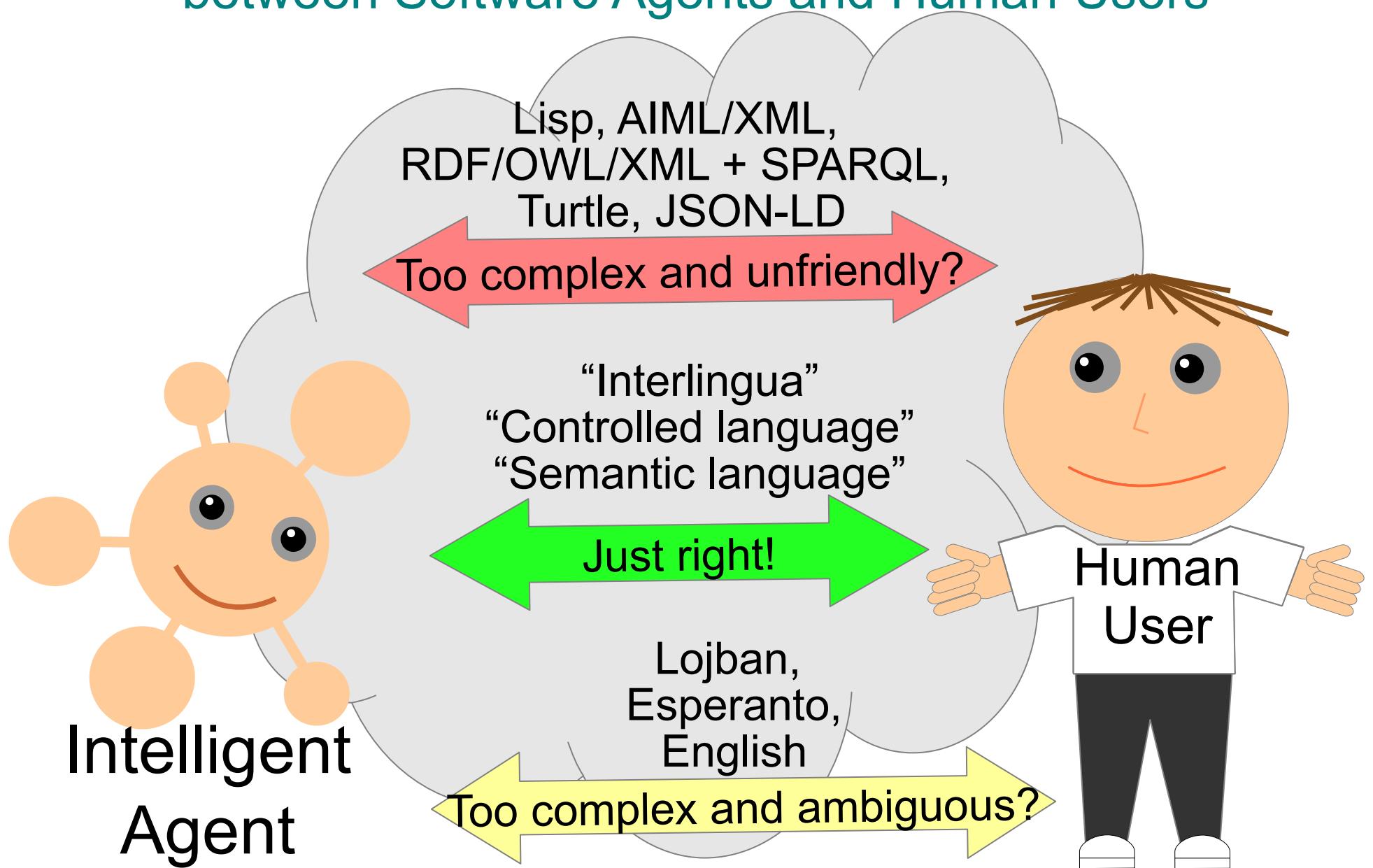
http://www.math.nsc.ru/AP/ScientificDiscovery/PDF/muhortov_khlebnikov_vityaev_neuroinformatics_v6.pdf

<http://www.math.nsc.ru/AP/ScientificDiscovery/soft/FS.html>

<https://www.youtube.com/watch?v=985Fw3yKeOM>

<https://d0sl.org/en/>

Aigents® - “Semantic Language” for Knowledge Transfer between Software Agents and Human Users



Aigents® Language (AL) as a Graph Manipulation

Interrogation:

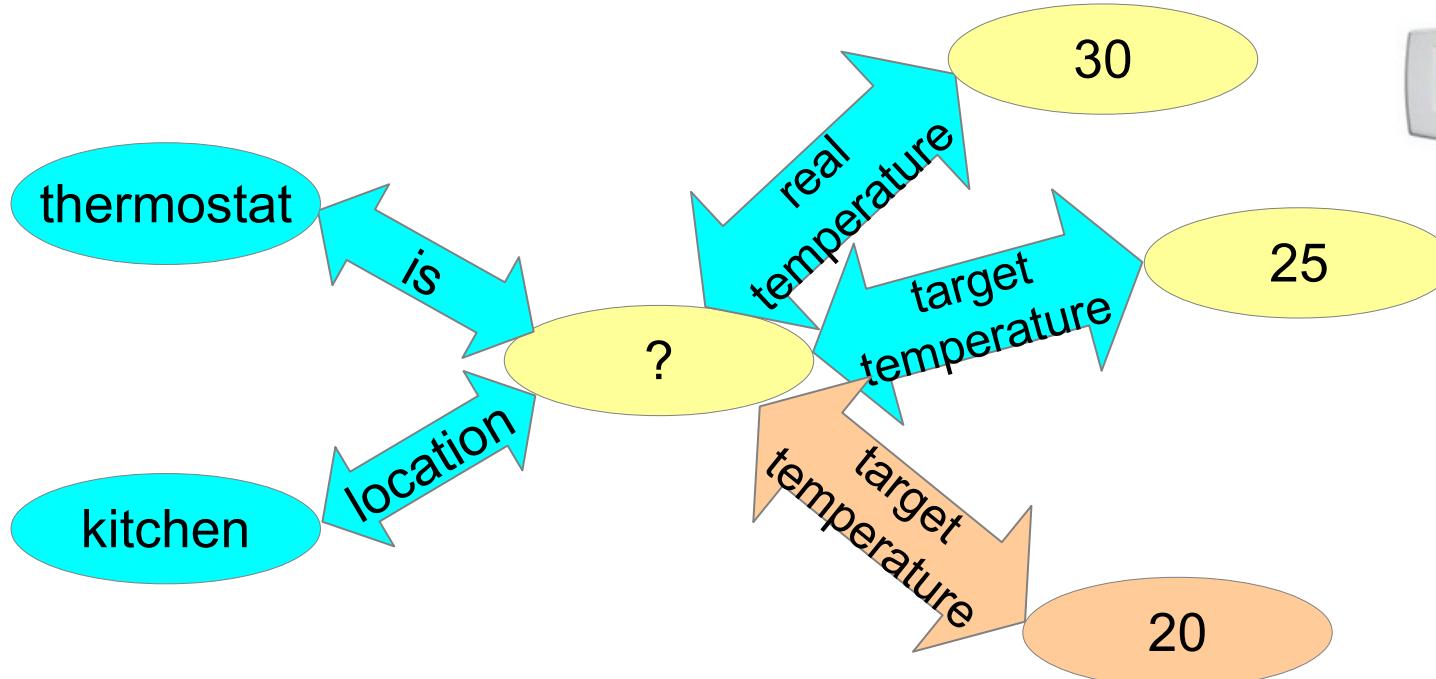
What is thermostat, location kitchen real temperature, target temperature?

Declaration:

Is thermostat, location kitchen real temperature 30, target temperature 25.

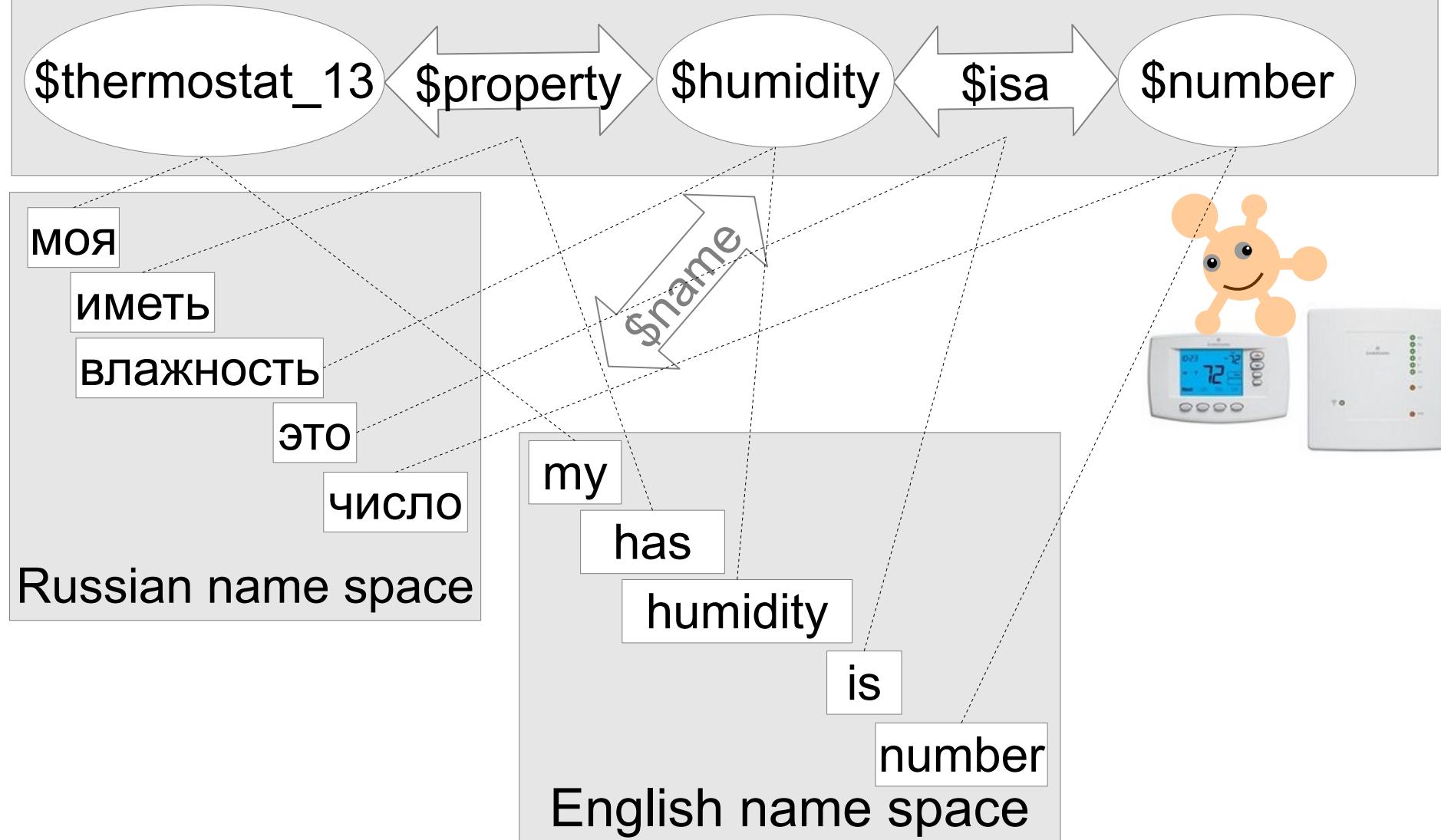
Direction:

Is thermostat, location kitchen target temperature 20!



Aigents® Language (AL) as a “Labeled Turtle”

Common domain-specific ontology for “controlled interlingua”

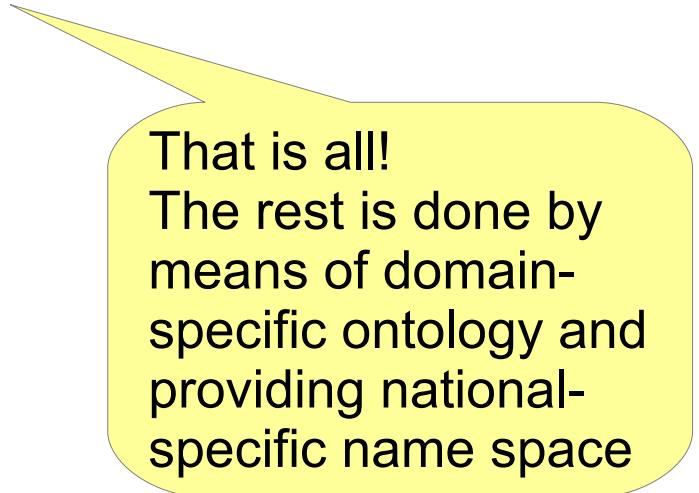


<http://aigents.com/papers/2019/ontologies-language-aigents-2019.pdf>

<http://aigents.com/papers/2015/ZONT-2015-Agent-Language-Kolonin.pdf>

Aigents® Language (AL) - EBNF

```
<message> := ( <statement> | <acknowledgement> )*
<acknowledgement> := ( 'ok' | ('true' | 'yes' | <number>) | ('no' | 'false' | 0) ) ''
<statement> := <interrogation> | <confirmation> | <declaration> | <direction>
<interrogation> := 'what' ? <expression> '?'          (* "open" incomplete graph *)
<confirmation> := 'if' ? <expression-set> '?'          (* "closed" complete graph *)
<declaration> := ( <expression-set> ) '.'           (* "closed" complete graph *)
<direction> := 'do' ? <expression-set> '!'           (* "closed" complete graph *)
<expression> := <term> ( ' ' <term>)*                (* separated by spaces *)
<expression-set> := <all-set> | <any-set> | <seq-set>      (* different kinds of sets *)
<term> := <negation>? ( <anonymous>? | <self> | <peer> | <id> | <name> | <value> | <qualifier> )
<qualifier> := <expression> | <expression-set>
<any-set> := <or-list> | ( '{' <or-list> '}' )
<all-set> := <and-list> | ( '(' <and-list> ')' )
<seq-set> := <next-list> | ( '[' <next-list> ']' )
<or-list> := <expression> ( (',' | 'or') <expression> )*
<and-list> := <expression> ( (',' | 'and') <expression> )*
<then-list> := <expression> ( (',' | 'next') <expression> )*
<negation> := 'not' | 'no' | '¬'
<anonymous> := ('there' ('is'|'are')) | 'any' | 'anything' ?
<self> := 'my'|'i'|'we'|'our'
<peer> := 'your'|'you'
<value> := <number> | <date> | <time> | <string>
```



That is all!
The rest is done by
means of domain-
specific ontology and
providing national-
specific name space

<http://aigents.com/papers/2019/ontologies-language-aigents-2019.pdf>
<http://aigents.com/papers/2015/ZONT-2015-Agent-Language-Kolonin.pdf>

Thank you and welcome!



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